-Digital Signal Processing-Discrete Fourier Transform

Lecture-19 -31-May-16

Difference b/w DTFT & DFT

• Recall the DTFT: $X(\omega) = \sum_{n=-\infty}^{\infty} x(n)e^{-j\omega n}$

- The Discrete time Fourier transform is the Fourier transform of a discrete time signal. Its output is continuous in frequency and periodic.
- The Discrete Fourier transform (DFT) is the sampled version of DTFT output.
- Such a representation is very useful for digital computations and for digital hardware implementations.

Discrete Fourier Series

• Let $\widetilde{x}[n]$ be a periodic sequence with a period N: $\widetilde{x}[n] = \widetilde{x}[n+N]$

• The Fourier series representation can be written as:

$$\tilde{x}[n] = \frac{1}{N} \sum_{k} \tilde{X}[k] e^{j(2\pi/N)kn}$$

• Which is decomposition of $\tilde{x}[n]$ into a sum of N harmonically related complex exponentials.

• The values of Discrete Fourier series coefficients, $\tilde{X}(K)$ may be derived by multiplying both sides of this expansion by $e^{-j2\pi nl/N}$, summing over one period and using the fact that the complex exponentials are orthogonal:

Discrete Fourier Series

$$\sum_{k=0}^{N-1} e^{-j2\pi n(k-l)/N} = \begin{cases} N & k = l \\ 0 & k \neq l \end{cases}$$

• The result is:

$$\tilde{X}(k) = \sum_{n=0}^{N-1} \tilde{x}(n) e^{-j2\pi nk/N}$$

• Note that the DFS coefficients are periodic with a period N: $\tilde{X}(k+N) = \tilde{X}(k)$

• Hence the DFT pair is:

$$X(k) = \sum_{n=0}^{N-1} x(n) e^{-j2\pi nk/N} \quad Analysis$$

$$x[n] = \frac{1}{N} \sum_{k} X[k] e^{j(2\pi/N)kn} \quad Synthesis$$

Example #1

Let us find the DFT representation for the sequence: 0

$$\tilde{x}(n) = \sum_{k=-\infty}^{\infty} x(n-10k)$$

where $x(n) = \begin{cases} 1 & 0 \le n < 5 \\ 0 & else \end{cases}$ • Note that $\tilde{x}[n]$ is a periodic sequence with a period N=10. Therefore, the DFS coefficients are: $\tilde{X}(k) = \sum_{n=0}^{9} \tilde{x}(n) e^{-j2\pi nk/10} = \sum_{n=0}^{4} e^{-j2\pi nk/10} = \frac{1 - e^{-j\pi k}}{1 - e^{-j\pi k/5}}$ Which, for $0 \le k \le 9$, may be simplified to : 0 $\tilde{X}(k) = \begin{cases} 5 & k = 0\\ \frac{2}{1 - e^{-j\pi k/5}} & k & odd\\ 0 & k & even \end{cases}$

Example #1 (cont.)

• The DFS coefficients for all other values of k may be found from the periodicity of $\tilde{X}(K)$ i.e., $\tilde{Y}(L, M) = \tilde{Y}(L)$

$$\tilde{X}(k+N) = \tilde{X}(k)$$

• For convenience we sometimes use: $W_N = e^{-j(2\pi/N)}$

• Analysis equation: $\widetilde{X}[k] = \sum_{n=0}^{N-1} \widetilde{X}[n]W_N^{kn}$

• Synthesis equation: $\widetilde{\mathbf{X}}[\mathbf{n}] = \frac{1}{N} \sum_{k=0}^{N-1} \widetilde{\mathbf{X}}[k] W_N^{-kn}$

Properties Of DFS

• Linearity:

• The DFS pair satisfies the property of linearity. That is:

$$\begin{array}{ccc} \widetilde{x}_{1}[n] & \xleftarrow{\text{DFS}} & \widetilde{X}_{1}[k] \\ \widetilde{x}_{2}[n] & \xleftarrow{\text{DFS}} & \widetilde{X}_{2}[k] \\ a\widetilde{x}_{1}[n] + b\widetilde{x}_{2}[n] & \xleftarrow{\text{DFS}} & a\widetilde{X}_{1}[k] + b\widetilde{X}_{2}[k] \end{array}$$

- Shift of a Sequence:
 - If a periodic sequence X[n] is shifted, the DFS coefficients are multiplied by a complex exponential. That is:

$$\begin{array}{ccc} \widetilde{x}[n] & \xleftarrow{\text{DFS}} & \widetilde{X}[k] \\ \widetilde{x}[n-m] & \xleftarrow{\text{DFS}} & e^{-j2\pi km/N} \widetilde{X}[k] \\ e^{j2\pi nm/N} \widetilde{x}[n] & \xleftarrow{\text{DFS}} & \widetilde{X}[k-m] \end{array}$$

Properties Of DFS (cont.)

- Duality:
 - It is stated as:

- Periodic Convolution:
 If \$\tilde{h}(n)\$ and \$\tilde{x}(n)\$ are periodic with a period N with DFS coefficients \$\tilde{H}(k)\$ and \$\tilde{X}(k)\$, respectively the sequence with DFS coefficients:
 \$\tilde{Y}(k) = \tilde{H}(k) \tilde{X}(k)\$ as follows:
 Is formed by periodically convolving \$\tilde{h}(n)\$ with \$\tilde{x}(n)\$ as follows:
 \$\tilde{y}(n) = \sum_{k=0}^{N-1} \tilde{h}(k) \tilde{x}(n-k)\$
 - Notationally, the periodic convolution of two sequences is written as:

$$\tilde{y}(n) = \tilde{h}(n) * \tilde{x}(n)$$

Properties Of DFS (cont.)

• Periodic Convolution: (cont.)

• The only difference between periodic and linear convolution is that, with periodic convolution, the sum is only evaluated over a single period, whereas with linear convolution the sum is taken over all values of k.

Graphical Periodic Convolution



Symmetry Properties

	Periodic Sequence (Period N)	DFS Coefficients (Period N)
1.	$\tilde{x}[n]$	$\tilde{X}[k]$ periodic with period N
2.	$\tilde{x}_1[n], \tilde{x}_2[n]$	$\tilde{X}_1[k], \tilde{X}_2[k]$ periodic with period N
3.	$a\tilde{x}_1[n] + b\tilde{x}_2[n]$	$a\tilde{X}_1[k] + b\tilde{X}_2[k]$
4.	$ ilde{X}[n]$	$N\tilde{x}[-k]$
5.	$\tilde{x}[n-m]$	$W_N^{km} \tilde{X}[k]$
6.	$W_N^{-\ell n} \tilde{x}[n]$	$ ilde{X}[k-\ell]$
7.	$\sum_{m=0}^{N-1} \tilde{x}_1[m]\tilde{x}_2[n-m] (\text{periodic convolution})$	$ ilde{X}_1[k] ilde{X}_2[k]$
8.	$\tilde{x}_1[n]\tilde{x}_2[n]$	$\frac{1}{N} \sum_{\ell=0}^{N-1} \tilde{X}_1[\ell] \tilde{X}_2[k-\ell] \text{(periodic convolution)}$
9.	$\tilde{x}^*[n]$	$ ilde{X}^*[-k]$

Symmetry Properties (cont.)

Periodic Sequence (Period N)	DFS Coefficients (Period N)
10. $\tilde{x}^*[-n]$	$ ilde{X}^*[k]$
11. $\mathcal{R}e\{\tilde{x}[n]\}$	$\tilde{X}_e[k] = \frac{1}{2}(\tilde{X}[k] + \tilde{X}^*[-k])$
12. $j\mathcal{J}m\{\tilde{x}[n]\}$	$\tilde{X}_o[k] = \frac{1}{2}(\tilde{X}[k] - \tilde{X}^*[-k])$
13. $\tilde{x}_e[n] = \frac{1}{2}(\tilde{x}[n] + \tilde{x}^*[-n])$	$\mathcal{R}e{\tilde{X}[k]}$
14. $\tilde{x}_o[n] = \frac{1}{2}(\tilde{x}[n] - \tilde{x}^*[-n])$	$j\mathcal{J}m\{\tilde{X}[k]\}$
Properties 15–17 apply only when $x[n]$ is real.	
15. Symmetry properties for $\tilde{x}[n]$ real.	$\begin{cases} \tilde{X}[k] = \tilde{X}^*[-k] \\ \mathcal{R}e{\tilde{X}[k]} = \mathcal{R}e{\tilde{X}[-k]} \\ \mathcal{J}m{\tilde{X}[k]} = -\mathcal{J}m{\tilde{X}[-k]} \\ \tilde{X}[k] = \tilde{X}[-k] \\ \lhd \tilde{X}[k] = -\sphericalangle \tilde{X}[-k] \end{cases}$

 $\mathcal{R}e{\tilde{X}[k]}$

 $j \mathcal{J}m\{\tilde{X}[k]\}$

- 16. $\tilde{x}_e[n] = \frac{1}{2}(\tilde{x}[n] + \tilde{x}[-n])$
- 17. $\tilde{x}_0[n] = \frac{1}{2}(\tilde{x}[n] \tilde{x}[-n])$

Discrete Fourier Transform

- The DFT is an important decomposition for sequences that are finite in length.
- Whereas the DTFT is a mapping from a sequence to a function of a continuous variable ω , $DTFT = V(i\omega)$
- The DFT is a mapping from a sequence, $x(n) \Leftrightarrow X(e^{j\omega})$ DFT = X(k),DFT = X(k),
- The DFT may be easily developed from the Discrete Fourier series representation for periodic sequences.
- The DFT pair was given as:

$$X[k] = \sum_{n=0}^{N-1} x[n]e^{-j(2\pi/N)kn}$$

$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j(2\pi/N)kn}$$

DFT Properties

• Linearity:

• If $x_1(n)$ and $x_2(n)$ have N-point DFTs $X_1(k)$ and $X_2(k)$, respectively: $ax_1(n) + bx_2(n) \stackrel{DFT}{\Leftrightarrow} aX_1(k) + bX_2(k)$

• In order to use this property it is important to make sure that the DFTs are the same length.

• Symmetry:

• If x(n) is real valued, X(k) is conjugate symmetric:

 $X(k) = X^*((-K)) = X^*((N-K))_N$

• If x(n) is imaginary, X(k) is conjugate anti-symmetric:

$$X(k) = -X^*((-K)) = -X^*((N-K))_N$$

• Circular Shift:

• The circular shift of a sequence x(n) is defined as follows: $X((n-n_0))_N R_N(n) = \tilde{x}(n-n_0)R_N(n)$

• Where n_0 is the amount of shift ad $R_N(n)$ is a rectangular window:

 $R_N(n) = \begin{cases} 1 & 0 \le n < N \\ 0 & else \end{cases}$

• A circular shift may be visualized as follows:



• Circular Shift: (cont.)



• Circular Shift: (cont.)

- If a sequence is circularly shifted, the DFT is multiplied by a complex exponential: $x(n-n_0)R_N(n) \stackrel{DFT}{\iff} W_N^{n_0k} X(k)$
- Similarly with a circular shift of the DFT, $X((k-k_0))_N$, the sequence is multiplied by a complex exponential:

$$W_N^{nk_0}$$
 $x(n)$ $X((k+k_0))_N$

• Circular Convolution:

- Let h(n) and x(n) be finite-length sequences of length N with N-point DFTs H(k) and X(k), respectively.
- The sequence that has a DFT equal to the product Y(k)=H(k)X(k) is:

$$y(n) = \left[\sum_{k=0}^{N-1} \tilde{h}(k)\tilde{x}(n-k)\right]R_N(n) = \left[\sum_{k=0}^{N-1} \tilde{h}(n-k)\tilde{x}(k)\right]R_N(n)$$

Circular Convolution: (cont.)

- Where $\tilde{x}(n)$ and $\tilde{h}(n)$ are the periodic extensions of the sequences x(n) and h(n), respectively.
- Because $\tilde{h}(n) = h(n)$ for $0 \le n \le N$. The previous equation can also be written as: $y(n) = \left[\sum_{k=0}^{N-1} h(k)\tilde{x}(n-k)\right]R_N(n)$
- The sequence y(n) in above equation in the N-point circular convolution of h(n) with x(n) and it is written as:
 y (n)=h(n) N x(n)= x(n) h(n)
- The circular convolution of two finite-length sequences h(n) and x(n) is equivalent to one period of the periodic convolution of the periodic sequences $\tilde{h}(n)$ and $\tilde{x}(n)$, (equation scan from book)

Example #2

• Example of circular convolution of two sequences:



Linear Convolution Using DFT

- The DFT provides a convenient way to perform convolutions without having to evaluate the convolution sum.
- If h(n) is N_1 points long and x(n) is N_2 points long, h(n) may be linearly convolved with x(n) as follows:
 - Pad the sequences h(n) and x(n) with zeros so that they are of length N≥N₁ + N₂ -1.
 - Find the N-point DFTs of h(n) and x(n).
 - Multiply the DFTs to form the product Y(k) = H(k) X(k).
 - Find the inverse DFT of Y(k).
- In spite of its computational advantages there are some difficulties with the DFT approach.
- For example, if x(n) is very long we must commit a significant amount of time computing very long DFTs and in the process accept very long processing delays.
- The solution to this problem is to use block convolution, which involves segmenting the signal to be filters x(n) into sections.

Linear Convolution Using DFT (cont.)

- Each section is then filtered with the Fir filter h(n), and the filtered sections are pieced together to form the sequence y(n).
- There are two block convolution techniques:
 - Overlap-add
 - Overlap-save

Overlap-add

- Let x(n) be a sequence that is to be convolved with a causal FIR filter h(n) of length L: $y(n) = h(n) * x(n) = \sum_{k=0}^{L-1} h(k) x(n-k)$
- Assume that x(n)=0 for n<0 and that the length of x(n) is much greater than L.
- In this method x(n) is partitioned into non-overlapping subsequences of length M as shown below:

Overlap-add (cont.)



Overlap-add (cont.)

• Thus x(n) may be written as a sum of shifted finite-length sequences of length M: $x(n) = \sum_{i=0}^{\infty} x_i (n - Mi)$

where
$$x_i = \begin{cases} x(n+Mi) & n = 0, 1, \dots, M-1 \\ 0 & else \end{cases}$$

• Therefore the linear convolution of x(n) with h(n) is:

$$y(n) = h(n) * x(n) = \sum_{i=0}^{\infty} x_i (n - Mi) * h(n) = \sum_{i=0}^{\infty} y_i (n - Mi)$$

Where y_i(n) is the linear convolution of x_i(n) with h(n):
y_i(n) = x_i(n)*h(n)

 Each sequence y_i(n) is of length N=L+M-1, it may be found by multiplying the N-point DFTs of x_i(n) and h(n)

Overlap-add (cont.)

• The reason for the name overlap-add is that for each I, the sequences y_i(n) and y_{i+1}(n) overlap at (N-M) points and in performing the sum these overlapping points are added.

Overlap-save

- This method takes advantage of the fact that the aliasing that occurs in circular convolution only affects a portion of the sequences.
- For example if x(n) and h(n) are finite length sequences of lengths L and n respectively, the linear convolution y(n) is a finite length sequences of lengths N+L-1.
- Therefore assuming that N>L, if we perform an N-point circular convolution of x(n) with h(n):

 $h(n) \otimes x(n) = \left[\sum_{k=-\infty}^{\infty} y(n+kN)\right] \mathcal{R}_{N}(n)$

- Because y(n+N) is the only term that is aliased into the interval $0 \le n \le N-1$, and because y(n+N) only overlaps the first L-1 values of y(n) and the remaining values in the circular convolution will not be aliased.
- In other words the first L-1 values of the circular convolution are not equal to the linear convolution, whereas the last M=N-L+1 values are the same. (shown in the figure below)
- Thus with the appropriate partitioning of the input sequence x(n), linear convolution may be performed by piecing together circular convolutions.

Overlap-save (cont.)

- The procedure is as follows:
 - Let $x_1(n)$ be the sequence:

$$x_{1}(n) = \begin{cases} 0 & 0 \le n < L-1 \\ x(n-L+1) & L-1 \le n \le N-1 \end{cases}$$

- Perform the N-point circular convolution of $x_1(n)$ with h(n) by forming the product $H(k)X_1(k)$ and then finding the inverse DFT, $y_1(n)$. The first L-1 values of the circular convolution are aliased and the last N-L+1 values corresponds to the linear convolution of x(n) with h(n). Due to the zero padding at the start of $x_1(n)$, these last N-L+1 values are the first N-L+1 values of y(n): $y(n) = y_1(n+L-1), \quad 0 \le n \le N-L$
- Let $x_2(n)$ be the N-point sequence that is extracted from x(n) with the first L-1 values overlapping with those of $x_1(n)$.
- Perform N-point circular convolution of $x_2(n)$ with h(n) by forming the product $H(k)X_2(k)$ and taking the inverse DFT. The first L-1 values of $y_2(n)$ are discarded and the final N-L+1 values are saved and concatenated with the saved values of $y_1(n)$: $y(n+N-L+1) = y_2(n+L-1), \quad 0 \le n \le N-L$

Overlap-save (cont.)

• Steps 3 and 4 are repeated until all of the values in the linear convolution have been evaluated.



Example #3

 Let us perform the four-point circular convolution of the two sequences h(n) and x(n), shown below:



Example #4

• Suppose we have two four-point sequences x[n] and h[n] as follows:

$$x[n] = \cos\left(\frac{\pi n}{2}\right), \quad n = 0, 1, 2, 3$$

 $h[n] = 2^n, \quad n = 0, 1, 2, 3$

- (a): Calculate the four-point DFT X[k].
- (b): Calculate the four-point DFT H[k].
- (c): Calculate $y[n] = x[n] \bigoplus h[n]$ by doing the circular convolution directly.
- (d): Calculate y[n] of Part (c) by multiplying the DFTs of x[n] and h[n] and performing an inverse DFT.