

# Linear Algebra

## General Vector Spaces

11<sup>th</sup> Aug 16

# Real Vector Spaces

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# Vector Space

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- A vector space is a nonempty set  $V$  of objects, called vectors.
- Two operations are defined on vectors called addition and multiplication by scalars (real numbers), subject to ten axioms listed below: (The axioms must hold for all vectors  $\mathbf{u}$ ,  $\mathbf{v}$  and  $\mathbf{w}$  in  $V$  and for all scalars  $c$  and  $d$ .)
  - The sum of  $\mathbf{u}$  and  $\mathbf{v}$ , denoted by  $\mathbf{u}+\mathbf{v}$ , is in  $V$ .
  - $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$
  - $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$
  - There is a **zero** vector  $\mathbf{0}$  in  $V$  such that  $\mathbf{u} + \mathbf{0} = \mathbf{u}$ .
  - For each  $\mathbf{u}$  in  $V$ , there is a vector  $-\mathbf{u}$  in  $V$  such that  $\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$ .
  - The scalar multiple of  $\mathbf{u}$  by  $c$ , denoted by  $c\mathbf{u}$ , is in  $V$ .
  - $c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$ .
  - $(c + d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$
  - $c(d\mathbf{u}) = (cd)\mathbf{u}$
  - $1\mathbf{u} = \mathbf{u}$

# Vector Space (cont.)

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- For Example: The zero vector space
- Let  $V$  consist of a single object, which we denote by  $\mathbf{0}$  and define:
- $\mathbf{0} + \mathbf{0} = \mathbf{0}$  and  $k\mathbf{0} = \mathbf{0}$  for all scalars  $k$ .
- This is known as **zero vector space**.

# Example #1

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- A vector space of 2 x 2 Matrices:
- let  $V$  be the set of 2 x 2 matrices with real entries and take the vector space operations on  $V$  to be the usual operation of matrix addition and scalar multiplication.

$$u + v = \begin{bmatrix} u_{11} & u_{12} \\ u_{21} & u_{22} \end{bmatrix} + \begin{bmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{bmatrix} = \begin{bmatrix} u_{11} + v_{11} & u_{12} + v_{12} \\ u_{21} + v_{21} & u_{22} + v_{22} \end{bmatrix}$$

$$ku = k \begin{bmatrix} u_{11} & u_{12} \\ u_{21} & u_{22} \end{bmatrix} = \begin{bmatrix} ku_{11} & ku_{12} \\ ku_{21} & ku_{22} \end{bmatrix}$$

- The set  $V$  is closed under addition and scalar multiplication because the foregoing operations produce 2 x 2 matrices as the end result.
- Thus it remains to confirm that Axioms 2,3,4,5,7,8,9 and 10 hold.

# Subspaces

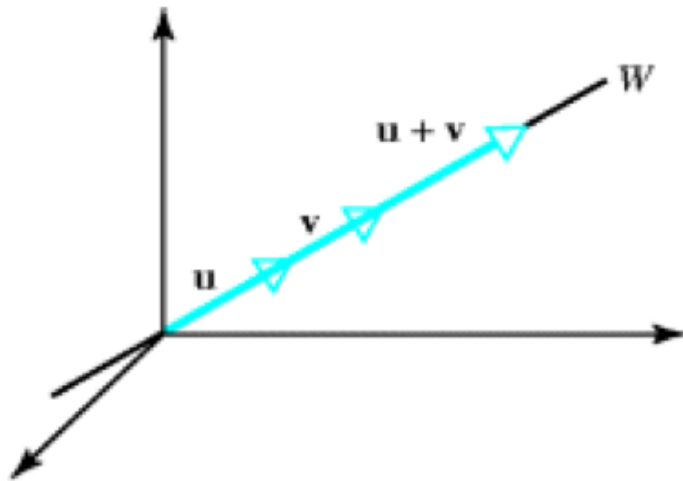
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- A subset  $W$  of a vector space  $V$  is called a subspace of  $V$  if  $W$  is itself a vector space under the addition and scalar multiplication.
- Theorem: If  $W$  is a set of one or more vectors in a vector space  $V$ , then  $W$  is a subspace of  $V$  if and only if the following conditions hold:
  - If  $\mathbf{u}$  and  $\mathbf{v}$  are vectors in  $W$ , then  $\mathbf{u}+\mathbf{v}$ , is in  $W$ .
  - If  $k$  is any scalar and  $\mathbf{u}$  is any vector in  $W$ , then  $k\mathbf{u}$  is in  $W$ .

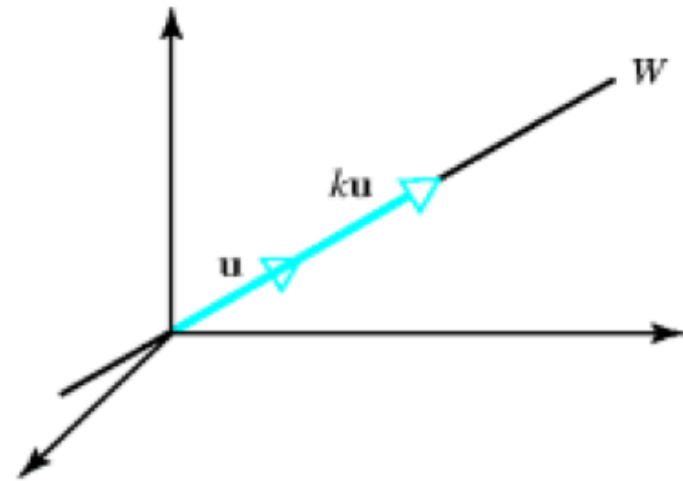
# Lines Through the Origin

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- Lines through the origin are subspaces of  $\mathbb{R}^2$  and  $\mathbb{R}^3$ :
  - If  $W$  is a line through the origin of either  $\mathbb{R}^2$  or  $\mathbb{R}^3$ , then adding two vectors on the line  $W$  or multiplying on the line  $W$  by a scalar produces another vector on the line  $W$ , so  $W$  is closed under addition and scalar multiplication.



(a)  $W$  is closed under addition.



(b)  $W$  is closed under scalar multiplication.

# A Subspace Spanned by a Set

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➤ Given  $\mathbf{v}_1$  and  $\mathbf{v}_2$  in a vector space  $V$ , let  $H = \text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$ . Show that  $H$  is a subspace of  $V$ :

➤ Solution:

➤ The zero vector is in  $H$ , since  $\mathbf{0} = 0\mathbf{v}_1 + 0\mathbf{v}_2$ . To show that  $H$  is closed under vector addition, take two arbitrary vectors in  $H$ , say

$$\mathbf{u} = s_1\mathbf{v}_1 + s_2\mathbf{v}_2 \quad \text{and} \quad \mathbf{w} = t_1\mathbf{v}_1 + t_2\mathbf{v}_2$$

➤ By axioms 2,3, and 8 for the vector space  $v$ ,

$$\begin{aligned} \mathbf{u} + \mathbf{w} &= (s_1\mathbf{v}_1 + s_2\mathbf{v}_2) + (t_1\mathbf{v}_1 + t_2\mathbf{v}_2) \\ &= (s_1 + t_1)\mathbf{v}_1 + (s_2 + t_2)\mathbf{v}_2 \end{aligned}$$

➤ So  $\mathbf{u} + \mathbf{w}$  is in  $H$ . Furthermore, if  $c$  is any scalar, then by Axioms 7 and 9:

$$c\mathbf{u} = c(s_1\mathbf{v}_1 + s_2\mathbf{v}_2) = (cs_1)\mathbf{v}_1 + (cs_2)\mathbf{v}_2$$



# A Subspace Spanned by a Set

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- Example continued:
- Which shows that  $cu$  is in  $H$  and  $H$  is closed under scalar multiplication. Thus  $H$  is a subspace of  $V$ .
- Theorem: If  $\mathbf{v}_1, \dots, \mathbf{v}_p$  are in a vector space  $V$ , then  $\text{Span} \{\mathbf{v}_1, \dots, \mathbf{v}_p\}$  is a subspace of  $V$ .

# Example #2

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➤ Let  $H$  be the set of all vectors of the form  $(a-3b, b-a, a, b)$ , where  $a$  and  $b$  are arbitrary scalars. That is, let  $H = \{(a-3b, b-a, a, b) : a \text{ and } b \text{ in } \mathbb{R}\}$ . Show that  $H$  is a subspace of  $\mathbb{R}^4$ .

➤ Solution:

➤ Write the vectors in  $H$  as column vectors. Then an arbitrary vector in  $H$  has the form:

$$\begin{bmatrix} a-3b \\ b-a \\ a \\ b \end{bmatrix} = a \begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \end{bmatrix} + b \begin{bmatrix} -3 \\ 1 \\ 0 \\ 1 \end{bmatrix}$$

$\uparrow$   $\uparrow$   
 $v_1$   $v_2$

➤ This calculation shows that  $H = \text{Span} \{\mathbf{v}_1, \mathbf{v}_2\}$ , where  $\mathbf{v}_1$  and  $\mathbf{v}_2$  are the vectors indicated above. Thus  $H$  is a subspace of  $\mathbb{R}^4$  by Theorem 1.

# Definitions

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- Definition 1: If  $\mathbf{w}$  is a vector space  $V$ , then  $\mathbf{w}$  is said to be a linear combination of the vectors  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r$  in  $V$  if  $\mathbf{w}$  can be expressed in the form:

$$\mathbf{w} = k_1\mathbf{v}_1 + k_2\mathbf{v}_2 + \dots + k_r\mathbf{v}_r$$

- Where  $k_1, k_2, \dots, k_r$  are scalars. These scalars are called the coefficients of the linear combination.
- Definition 2: the subspace of a vector space  $V$  that is formed from all possible linear combinations of the vectors in a nonempty set  $S$  is called the span of  $S$  and we say that the vectors in  $S$  span that subspace. If  $S = \{\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_r\}$ , then we denote the span of  $S$  by:

$$\text{span}\{\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_r\} \quad \text{or} \quad \text{span}(S)$$

# Example #3

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➤ Consider the vectors  $\mathbf{u} = (1, 2, -1)$  and  $\mathbf{v} = (6, 4, 2)$  in  $\mathbb{R}^3$ . Show that  $\mathbf{w} = (9, 2, 7)$  is a linear combination of  $\mathbf{u}$  and  $\mathbf{v}$  and that  $\mathbf{w}' = (4, -1, 8)$  is not a linear combination of  $\mathbf{u}$  and  $\mathbf{v}$ .

➤ Solution:

➤ In order for  $\mathbf{w}$  to be linear combination of  $\mathbf{u}$  and  $\mathbf{v}$ , there must be scalars  $k_1$  and  $k_2$  such that  $\mathbf{w} = k_1\mathbf{u} + k_2\mathbf{v}$ ; that is:

$$(9, 2, 7) = k_1(1, 2, -1) + k_2(6, 4, 2)$$

*or*

$$(9, 2, 7) = (k_1 + 6k_2, 2k_1 + 4k_2, -k_1 + 2k_2)$$

➤ Equating corresponding components gives:

$$k_1 + 6k_2 = 9$$

$$2k_1 + 4k_2 = 2$$

$$-k_1 + 2k_2 = 7$$

# Example #3 (cont.)

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- Solving this system using Gaussian elimination yields  $k_1 = -3$ ,  $k_2 = 2$ , so:

$$w = -3u + 2v$$

- Similarly, for  $\mathbf{w}'$  to be a linear combination of  $\mathbf{u}$  and  $\mathbf{v}$ , there must be scalars  $k_1$  and  $k_2$  such that  $\mathbf{w}' = k_1\mathbf{u} + k_2\mathbf{v}$ ; that is,

$$(4, -1, 8) = k_1(1, 2, -1) + k_2(6, 4, 2)$$

or

$$(4, -1, 8) = (k_1 + 6k_2, 2k_1 + 4k_2, -k_1 + 2k_2)$$

- Equating corresponding components gives:

$$k_1 + 6k_2 = 4$$

$$2k_1 + 4k_2 = -1$$

$$-k_1 + 2k_2 = 8$$

- This system of equations is inconsistent, so no such scalars  $k_1$  and  $k_2$  exist. Consequently,  $\mathbf{w}'$  is not a linear combination of  $\mathbf{u}$  and  $\mathbf{v}$ .

# Example #4

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- Determine whether  $\mathbf{v}_1 = (1,1,2)$ ,  $\mathbf{v}_2 = (1,0,1)$  and  $\mathbf{v}_3 = (2,1,3)$  span the vector space  $\mathbb{R}^3$ .
- Solution:
- We must determine whether an arbitrary vector  $\mathbf{b} = (b_1, b_2, b_3)$  in  $\mathbb{R}^3$  can be expressed as a linear combination:  $\mathbf{b} = k_1\mathbf{v}_1 + k_2\mathbf{v}_2 + k_3\mathbf{v}_3$  of the vectors  $\mathbf{v}_1$ ,  $\mathbf{v}_2$  and  $\mathbf{v}_3$ . Expressing this equation in terms of components gives:

$$(b_1, b_2, b_3) = k_1(1,1,2) + k_2(1,0,1) + k_3(2,1,3)$$

or

$$(b_1, b_2, b_3) = (k_1 + k_2 + 2k_3, k_1 + k_3, 2k_1 + k_2 + 3k_3)$$

or

$$k_1 + k_2 + 2k_3 = b_1$$

$$k_1 + k_3 = b_2$$

$$2k_1 + k_2 + 3k_3 = b_3$$

# Example #4 (cont.)

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- Thus, our problem reduces to ascertaining whether this system is consistent for all values of  $b_1$ ,  $b_2$ , and  $b_3$ .
- One way of doing this is to use the fact that the system is consistent if and only if its coefficient matrix:

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 0 & 1 \\ 2 & 1 & 3 \end{bmatrix}$$

- Has a nonzero determinant.

# Thankyou

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