

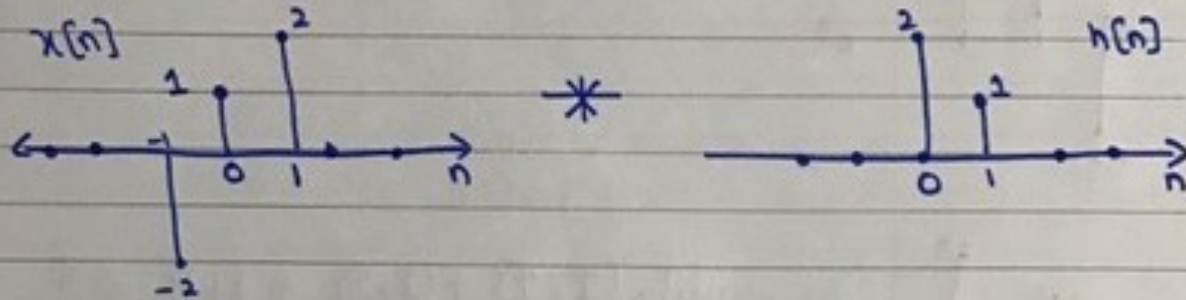
Lecture Notes

31st October 2016

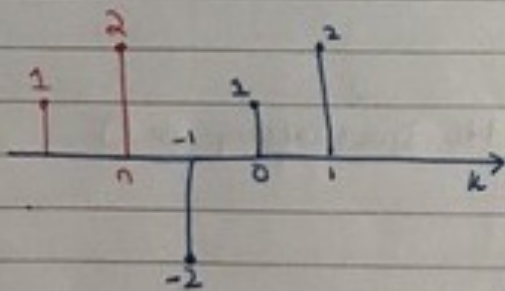
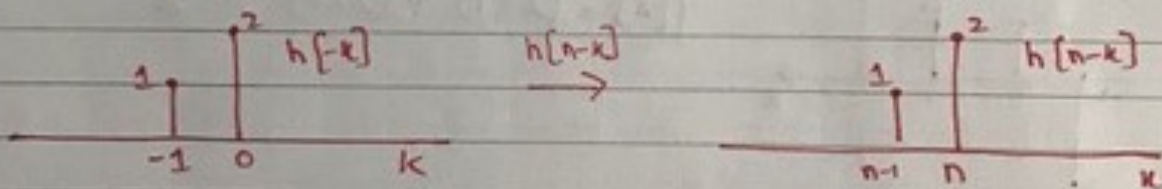
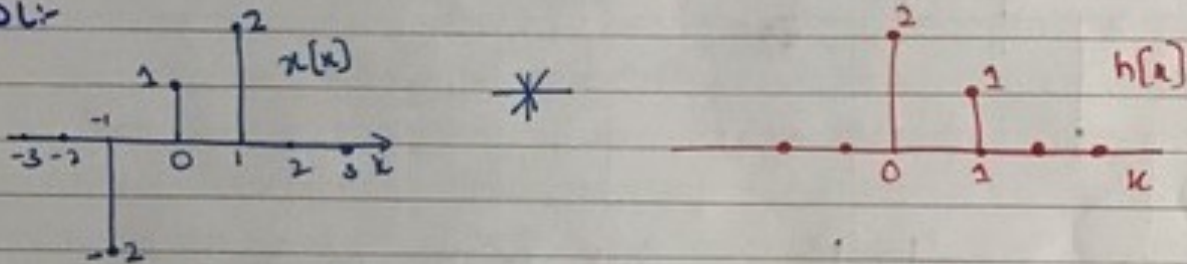
Monday (31st Oct 2016)

LECTURE #5

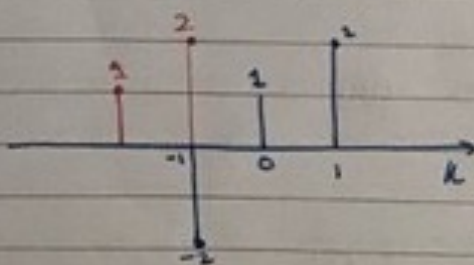
CONVOLUTION EXAMPLES:-
EXAMPLES #1:-



SOL:-

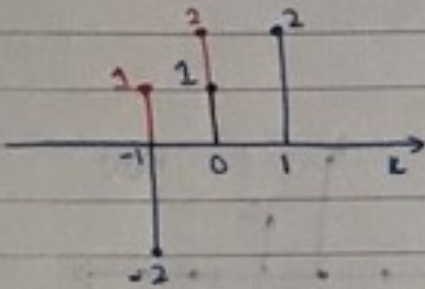


$$n < -1 \Rightarrow \sum_{k=-\infty}^{\infty} x[k] h[n-k] = \text{No overlap} \\ \Rightarrow \text{ping} \Rightarrow 0$$

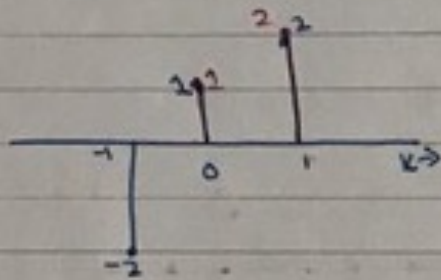


$$y[n] = 2 \times (-2) \Rightarrow -4$$

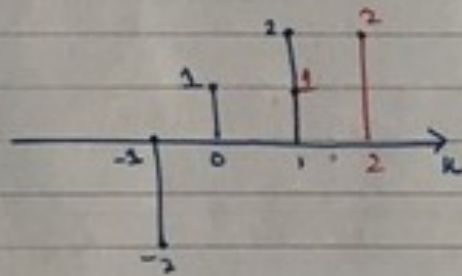
Day/Date



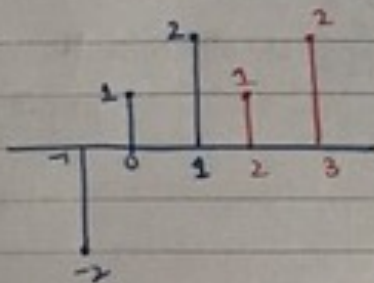
$$y[0] = 1 \times (-2) + (2 \times 1) \Rightarrow -2 + 2 \Rightarrow 0$$



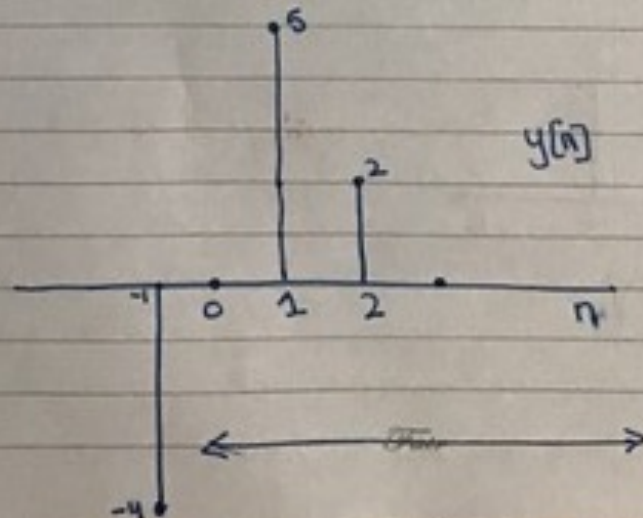
$$y[1] = (1 \times 1) + (2 \times 2) \Rightarrow 1 + 4 \Rightarrow 5$$



$$y[2] = (2 \times 1) + (2 \times 0) \Rightarrow 2$$

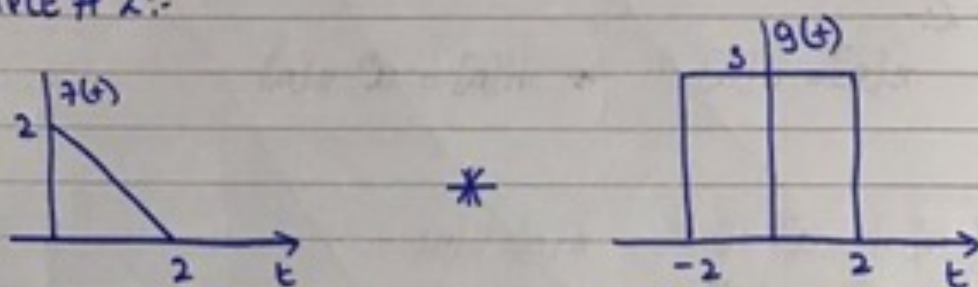


$$y[3] \Rightarrow \text{No overlapping} \Rightarrow 0$$



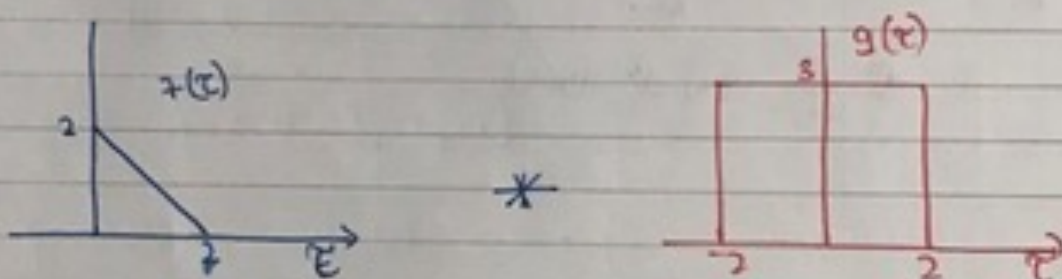
Day/Date

EXAMPLE # 2:-

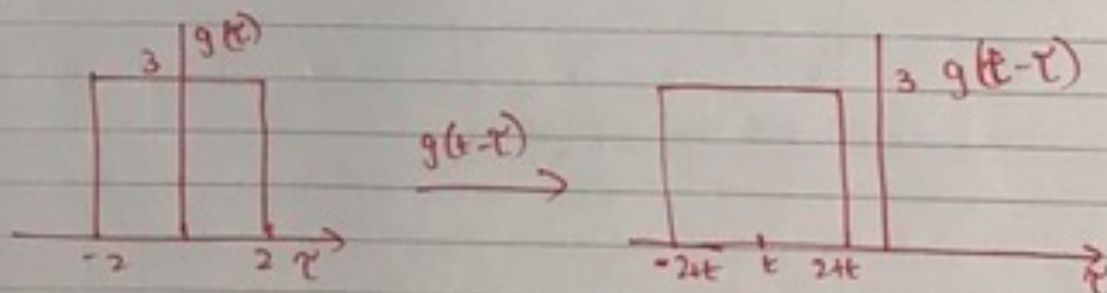


SOL:-

Step #1:- replace t with τ .

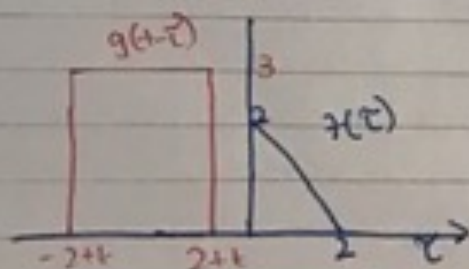


Step #2:- Flip & Shift one signal. Here we are flipping and shifting $g(\tau)$.



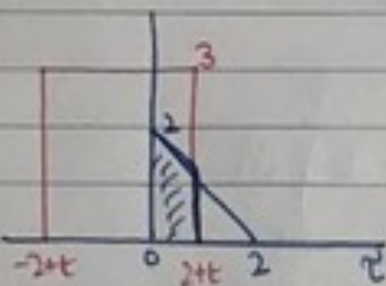
Step #3:- Start overlapping:

1 $\rightarrow t < -2$



No overlapping $\therefore y(t) = 0$

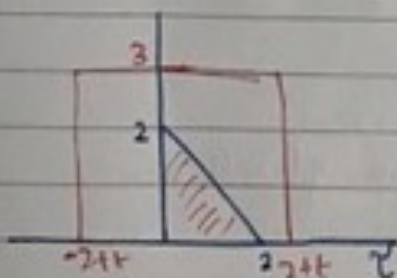
$$2 \rightarrow -2 \leq t < 0$$



$$\begin{aligned}
 y(t) &= \int_0^{2t} 3(-\tau+2) d\tau \\
 &= -3 \int_0^{2t} \tau d\tau + 6 \int_0^{2t} d\tau \\
 &= -3 \left[\frac{\tau^2}{2} \right]_0^{2t} + 6 \left[\tau \right]_0^{2t} \\
 &= -3 \left[\frac{(2t)^2}{2} - 0 \right] + 6 [2t - 0] \\
 &= -3 \left[\frac{4+4t+t^2}{2} \right] + 6(2t) \\
 &= \frac{-12-12t-3t^2}{2} + 12+6t \\
 &= \frac{-12-12t-3t^2+24+12t}{2} \\
 &= \frac{-3t^2+12}{2} \Rightarrow \frac{-3t^2}{2} + \frac{12}{2}
 \end{aligned}$$

$$y(t) = \frac{-3t^2}{2} + 6$$

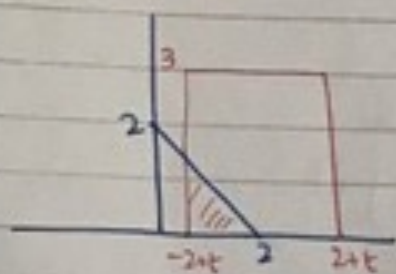
$$3 \rightarrow 0 \leq t < 2$$



$$\begin{aligned}
 y(t) &= \int_0^2 3(-\tau+2) d\tau \\
 &= -3 \int_0^2 \tau d\tau + 6 \int_0^2 d\tau \\
 &= -3 \left[\frac{\tau^2}{2} \right]_0^2 + 6 \left[\tau \right]_0^2 \\
 y(t) &= -3 \left[\frac{4}{2} \right] + 6 [2] = -6 + 12 \Rightarrow 6
 \end{aligned}$$

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4 → $2 \leq t < 4$



$$y(t) = \int_{-2+t}^2 3(-\tau+2) d\tau$$

$$= -3 \int_{-2+t}^2 \tau d\tau + 6 \int_{-2+t}^2 d\tau$$

$$= -3 \left[\frac{\tau^2}{2} \right]_{-2+t}^2 + 6 [\tau]_{-2+t}^2$$

$$= -3 \left[\frac{4}{2} - \frac{(-2+t)^2}{2} \right] + 6[2+t] - 3 \left[\frac{4^2}{2} - \frac{(t-2)^2}{2} \right] + 6[2 - (-2+t)]$$

$$= -3 \left[\frac{-t^2+4t}{2} \right] + 24-6t - 3 \left[2 - \frac{t^2-4t+4}{2} \right] + 6[2+2-t]$$

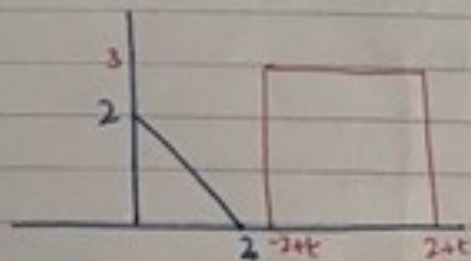
$$= \frac{3t^2}{2} - \frac{12t}{2} + 24-6t = -6 + \frac{3t^2-12t+12}{2} + 6[4-t]$$

$$= \frac{3t^2}{2} - 6t + 24 - 6t = -6 + \frac{3t^2-12t+12}{2} + 24 - 6t$$

$$= \frac{3t^2}{2} + 24 - 6t \text{ Ans} = \frac{12 + 3t^2 - 12t + 12 + 48 - 12t}{2}$$

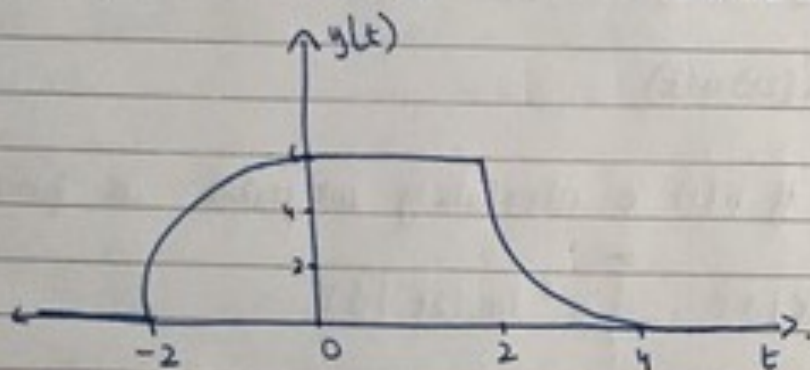
$$= \frac{3t^2 + 48}{2} \Rightarrow \frac{3t^2}{2} + 24$$

5 → $t \geq 4$



No overlapping so $y(t)=0$.

$$y(t) = f(t) * g(t) = \begin{cases} 0 & \text{for } t < -2 \\ \frac{-3t^2 + 6}{2} & \text{for } -2 \leq t < 0 \\ 6 & \text{for } 0 \leq t < 2 \\ \frac{3t^2 - 12t + 24}{2} & \text{for } 2 \leq t < 4 \\ 0 & \text{for } t \geq 4 \end{cases}$$



EXAMPLE #3:-

$$x(t) = e^{-at} u(t) \quad * \quad h(t) = e^{-bt} u(t), \quad b \neq a$$

SOL:-

$$\begin{aligned} y(t) &= \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau \\ &= \int_{-\infty}^{\infty} e^{-a\tau} u(\tau) e^{-b(t-\tau)} u(t-\tau) d\tau = \int_{-\infty}^{\infty} e^{-a\tau} e^{-bt} e^{+b\tau} u(\tau) u(t-\tau) d\tau \\ &= e^{-bt} \int_0^t e^{-a\tau} e^{b\tau} d\tau, \quad t > 0 \\ &= e^{-bt} \int_0^t e^{b\tau - a\tau} d\tau = e^{-bt} \left[\frac{e^{(a+b)\tau}}{-a+b} \right]_0^t \\ &= e^{-bt} \left[\frac{e^{(a+b)t}}{-a+b} - 0 \right] = e^{-bt} \left[\frac{e^{-at} e^{bt}}{-a+b} \right] \\ &= e^{-bt} \left[\frac{e^{(a+b)t}}{-a+b} - \frac{e^0}{-a+b} \right] = e^{-bt} \left[\frac{e^{-at} e^{bt}}{-a+b} - \frac{1}{-a+b} \right] \\ &= \frac{e^{-at} e^{-b(t-a)} - e^{-bt}}{-a+b} \Rightarrow \frac{e^{-at} - e^{-bt}}{b-a} u(t) \end{aligned}$$

when $t < 0$ then $y(t) = 0$.

EXERCISE PROBLEMS:-

PROBLEM #1:-

Which of the following impulse responses correspond(s) to stable LTI systems?

a) $h(t) = e^{-t} \cos(2t) u(t)$

Sol:-

We determine if $h(t)$ is absolutely integrable as follows:-

$$\int_{-\infty}^{\infty} |h(\tau)| d\tau = \int_0^{\infty} e^{-\tau} |\cos(2\tau)| d\tau$$

This integrable is clearly finite valued because $e^{-t} |\cos(2t)|$ is an exponentially decaying function in the range $0 \leq t < \infty$. Therefore $h(t)$ is the impulse response of the stable LTI system.



b) $h[n] = 3^n u[-n+10]$

Sol:-

We have to determine if $h[n]$ is absolutely summable as follows:-

$$\sum_{-\infty}^{\infty} |h[k]| = \sum_{-\infty}^{10} 3^k \approx \frac{3^{11}}{2}$$

Therefore $h[n]$ is the impulse response of a stable LTI system.

PROBLEM #2:-

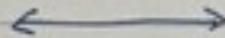
Determine whether each system is causal and/or stable:-

a) $h[n] = 5^n u[3-n]$

Sol:-

$$\sum_{n=-\infty}^3 5^n \Rightarrow \frac{625}{4} < \infty \text{ so it is stable.}$$

But not causal as $h[n] \neq 0$ for $n < 0$.



b) $h(t) = e^{-4t} u(t-2)$

Sol:-

It is causal because $h(t) = 0$ for $t < 0$.

$$\int_{-\infty}^{\infty} e^{-4t} u(t-2) dt \Rightarrow \frac{e^{-8}}{4} < \infty \text{ so it is stable.}$$