



# ISRA UNIVERSITY

Islamabad Campus

Department of Electrical Engineering

Program: B.E. (Electrical)

Semester - Fall 2016

EL313- Signal & Systems

**Assignment – 2 Solution**

**Marks: 20**

**Due Date: 07/11/2016**

**Handout Date: 28/10/2016**

Question # 1:

For the discrete time system given below:

$$y(n) = x(n) + nx(n - 2)$$

Check the following:

1. System with/ Without Memory
2. Invertible/ Non-invertible
3. Causality
4. Time Invariant or not
5. Linearity

Solution:

1. System with/ Without Memory  
The output  $y(n)$  depends on the past value as well so the system is not memoryless.
2. Invertible/ Non-invertible  
The system is non-invertible.
3. Causality  
The output  $y(n)$  depends on the present input  $x(n)$  and the past input  $x(n-2)$ . Therefore the system is causal.
4. Time Invariant or not  
If the input is delayed by 'k' samples the output will be:  
$$y(n, k) = x(n - k) + nx(n - k - 2) \rightarrow (1)$$
  
Now if we delay  $y(n)$  by 'k' samples, we get:  
$$y(n - k) = x(n - k) + (n - k)x(n - k - 2) \rightarrow (2)$$
  
Hence,  $y(n, k) \neq y(n - k)$ . Therefore the system is Time Variant.
5. Linearity

Let's consider a signal:

$$x(n) = ax_1(n) + bx_2(n)$$

Where  $y_1(n) = x_1(n) + nx_1(n - 2)$  &  $y_2(n) = x_2(n) + nx_2(n - 2)$

Then:

$$ay_1(n) + by_2(n) = ax_1(n) + anx_1(n - 2) + bx_1(n) + bnx_1(n - 2)$$

$$ay_1(n) + by_2(n) = a(x_1(n) + nx_1(n - 2)) + b(x_1(n) + nx_1(n - 2))$$

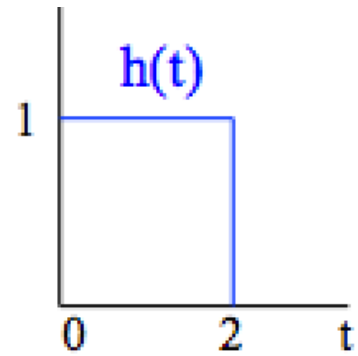
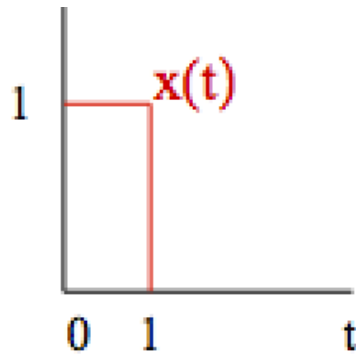
$$y_3(n) = ay_1(n) + by_2(n)$$

Hence the system is linear.

---

Question # 2:

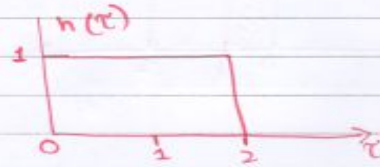
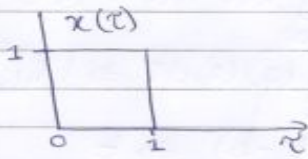
Convolve the two Continuous-Time Signals given below:



Solution:

### STEP #1:-

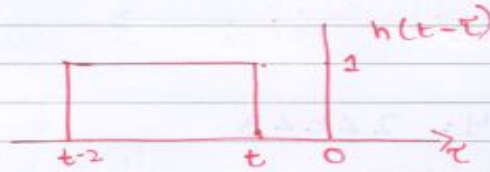
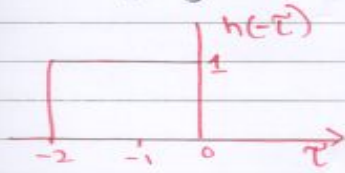
Change the subscript:  $t \rightarrow \tau$



### STEP #2:-

Flip <sup>and shift</sup> any one of the above signals

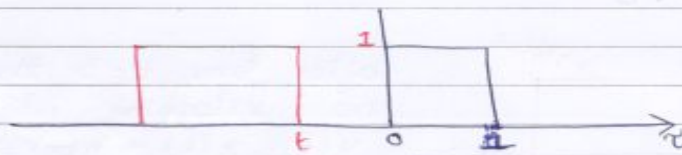
Flipping & Shifting  $h(\tau)$



### STEP #3:-

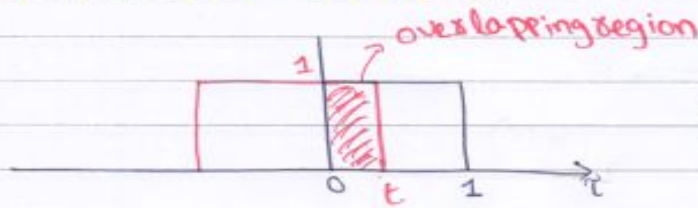
Start sliding  $h(t-\tau)$  on  $x(\tau)$  and integrate.

• INTERVAL #1 :  $t < 0$



No overlapping so  $y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau \Rightarrow 0$

• INTERVAL #2:  $0 < t < 1$ .



$$y(t) = \int_0^t x(\tau) h(t-\tau) d\tau$$

$$= \int_0^t (1)(1) d\tau \Rightarrow |\tau|_0^t$$

$$y(t) = (t-0) \Rightarrow t$$

• INTERVAL #3:  $1 < t < 2$

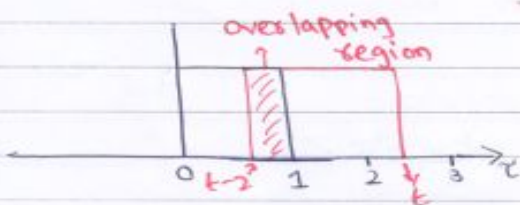


$$y(t) = \int_0^1 (1 \times 1) d\tau$$

$$= |\tau|_0^1 = 1-0$$

$$y(t) \Rightarrow 1$$

• INTERVAL #4:  $2 < t < 3$

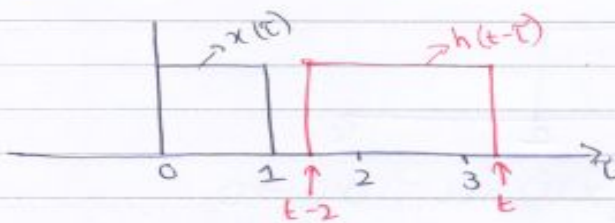


$$y(t) = \int_{t-2}^2 (1 \times 1) d\tau$$

$$= |\tau|_{t-2}^2 = 2 - (t-2)$$

$$y(t) = 2 - t + 2 \Rightarrow 4 - t$$

• INTERVAL #5:  $t > 3$

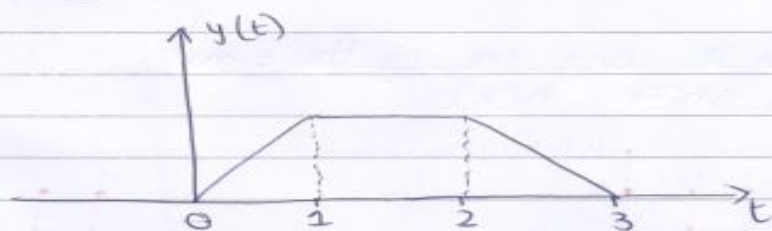


after time  $t=3$  there is no overlapping. integral is 0.  
 $y(t) = x(t) * h(t) \Rightarrow 0$

STEP #4:

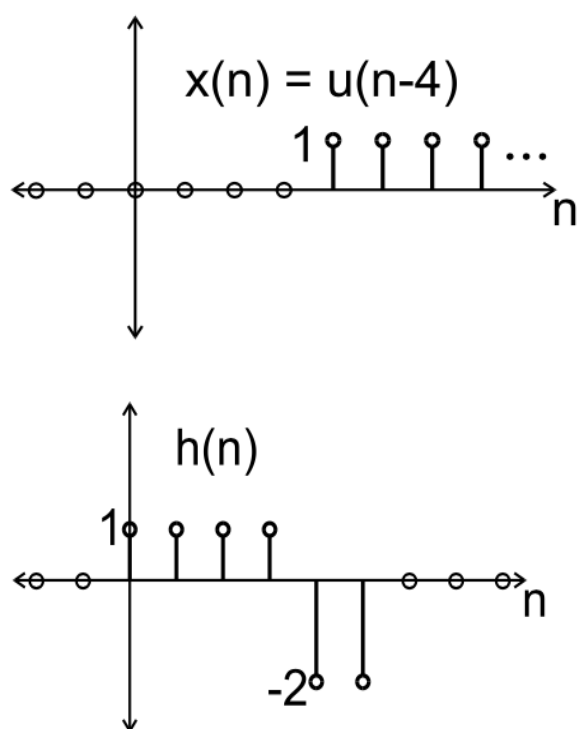
Draw the final signal.

$$y(t) = \begin{cases} 0 & t < 0 \\ t & 0 < t < 1 \\ 1 & 1 < t < 2 \\ 3-t & 2 < t < 3 \\ 0 & t > 3 \end{cases}$$



Question # 3:

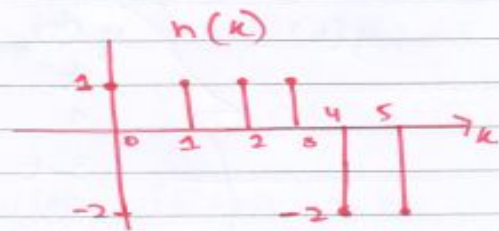
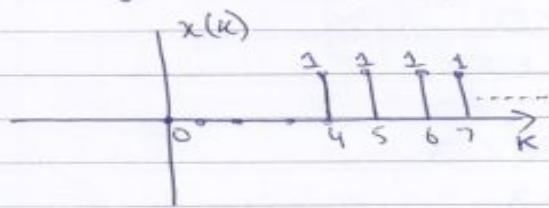
Convolve the two Discrete-Time Signals given below:



Solution:

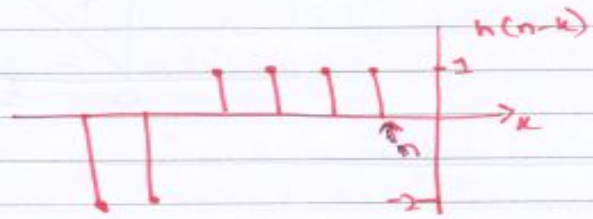
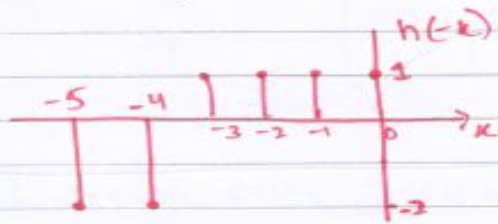
### STEP #1:-

Change the subscripts.  $n \rightarrow k$



### STEP #2:-

Flip & shift any one of the signal.  
Let's flip & shift  $h(k)$ .



### STEP #3:-

Start sliding  $h(n-k)$  on  $x(k)$  and solve the convolution sum.  
As we know that  $x(k)$  starts from  $k=4$  and continues to infinity as its unit step function, hence our overlapping will start from  $n=4$  and onwards.

#### §. $n < 4$

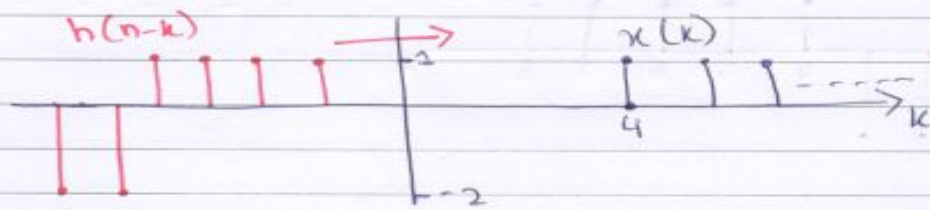
For example shifting  $h(n-k)$  to the right.

A plot showing the shifted signal  $h(n-k)$  for  $n < 4$ . The horizontal axis is labeled  $k$  and has tick marks at 4 and  $n$ . The vertical axis has tick marks at 1 and -2. The signal is 1 for  $k=n-3, n-2, n-1, n$  and -2 for  $k=n-4, n-5$ . The signal is 0 for  $k > n$ . A red arrow labeled  $n$  points to the  $k$ -axis at the position of the signal's start.

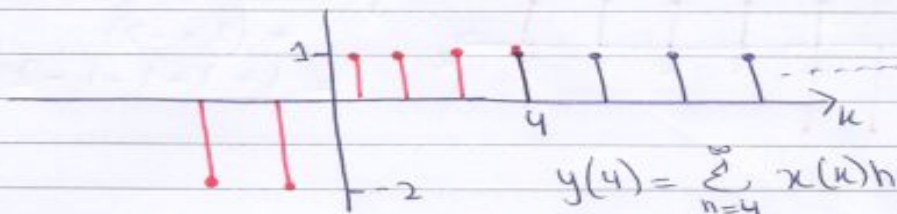
There is no overlapping so  $y(n) = 0$ .



→ Now when  $n \geq 4$ , we see that  $h(n-k)$  slides and overlaps with  $x(k)$  and hence overlapping starts.



• when  $n=4$ :



$$y(4) = \sum_{n=4}^{\infty} x(k)h(n-k)$$

$$= (1) \times (1) \Rightarrow 1$$

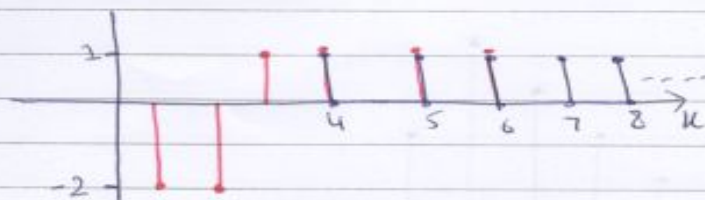
• when  $n=5$ :



$$y(5) = \sum_{n=4}^{\infty} x(k)h(n-k)$$

$$= (1 \times 1) + (1 \times 1) \Rightarrow 1 + 1 = 2$$

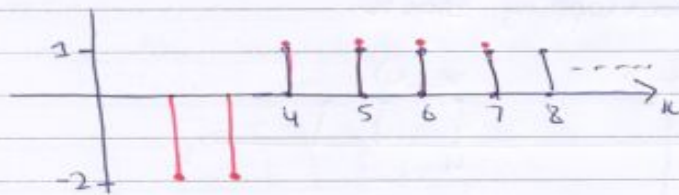
• when  $n=6$ :



$$y(6) = (1 \times 1) + (1 \times 1) + (1 \times 1)$$

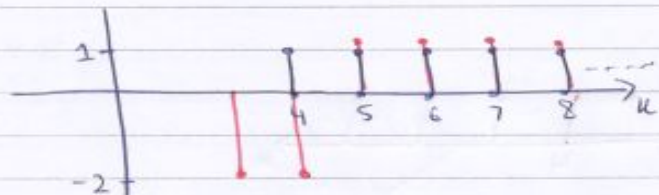
$$= 1 + 1 + 1 \Rightarrow 3$$

• when  $n=7$ :



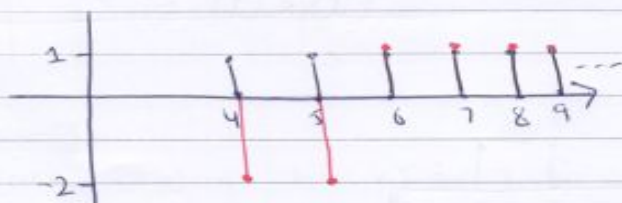
$$y(7) = (1 \times 1) + (1 \times 1) + (1 \times 1) + (1 \times 1) \\ = 1 + 1 + 1 + 1 \Rightarrow 4$$

• when  $n=8$ :



$$y(8) = (1 \times 1) + (1 \times 1) + (1 \times 1) + (1 \times 1) \\ + (1 \times -2) \\ = 1 + 1 + 1 + 1 - 2 \Rightarrow 2$$

• when  $n \geq 9$ :

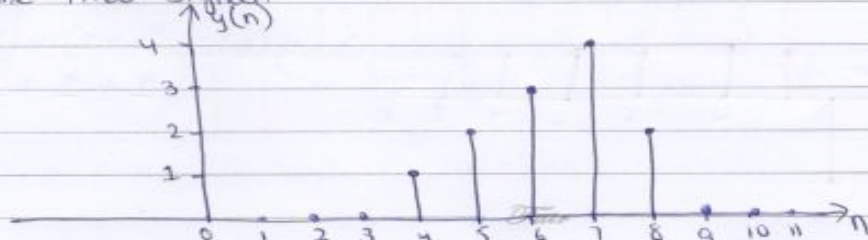


$$y(9) = (1 \times 1) + (1 \times 1) + (1 \times 1) + (1 \times 1) \\ + (1 \times -2) + (1 \times -2) \\ = 1 + 1 + 1 + 1 - 2 - 2 \\ y(9) = 4 - 2 - 2 \Rightarrow 0$$

As its summing over the entire length of the impulse response so  $y(n) = 1$  from  $n \geq 9$ .

Step #4:-

Plot the final signal.





**Good Luck**