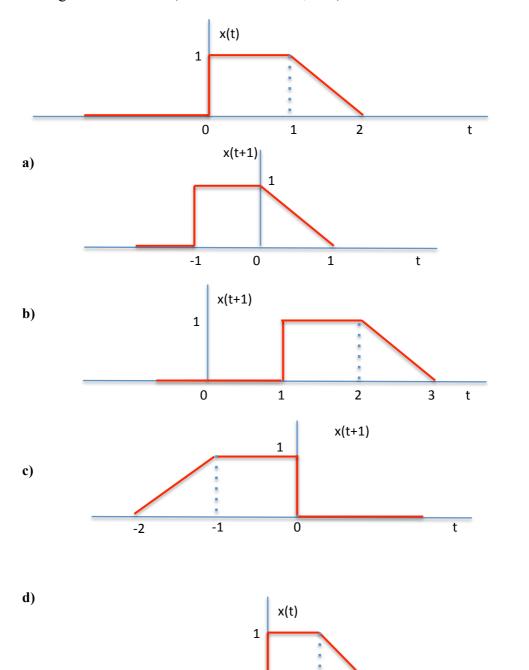
1.	<ul> <li>For a unit step function the value of the function should be:</li> <li>a) 0 for t &lt; 0 and 1 for t ≥ 0</li> <li>b) 0 for t &lt; 0 and -1 for t ≥ 0</li> <li>c) 0 everywhere except for the 0 itself</li> <li>d) None of the above</li> </ul> Answer: (a	1)
2.	A system which is linear is said to obey the rules of:  a) Scaling b) Additivity c) Both scaling and additivity d) None of the above  Answer: (c	)
3.	A time invariant system is a system whose output:  a) Increases with a delay in input b) Remains same with a delay in input c) Decreases with a delay in input d) Vanishes with a delay in input  Answer: (b	)
4.	<ul> <li>Signal is defined as:</li> <li>a) A quantitative description of a physical phenomenon, event or the process.</li> <li>b) A function represents a physical quantity or variable containing the information about the behavior and nature of the phenomenon.</li> <li>c) A device or a set of rules defining the functional relation between the input and output.</li> <li>d) Both (a) and (b)</li> </ul> Answer: (d	)
5.	<ul> <li>In a time shift operation, if t<sub>0</sub> &gt; 0 then:</li> <li>a) The time shift is known as advance.</li> <li>b) The time shift is known as delay.</li> <li>c) The signal is decimated.</li> <li>d) None of the above.</li> </ul> Answer: (b	)
6.	<ul> <li>If 0 &lt; a &lt; 1, the time scale of the resultant signal is:</li> <li>a) Decimated.</li> <li>b) Speedup.</li> <li>c) Slowed down.</li> <li>d) None of the above.</li> </ul> Answer: (c)	<b>:</b> )

7. For the signal shown below, if we shift it with  $t_0 = -1$ , then the result will be:



Answer: (a)

t

- **8.** A system is said to be defined as non-causal, when:
  - a) The output at the present depends on the input at an earlier time.
  - b) The output at the present does not depend on the factor of time at all.

0

0.5

1

- c) The output at the present depends on the input at a time instant in the future.
- d) The output at the present depends on the input at the current time.

Answer: (c)

9.	<ul><li>a)</li><li>b)</li><li>c)</li></ul>	function $y[n] = x[n-1] - x[n-4]$ memoryless? The system is memoryless. The system needs to have memory, so it is with memory. The system is neither memoryless nor with memory. None of the above.	Answer: (b)
10.	In real	exponential function if $\alpha > 0$ then the graph will:	
		Decrease exponentially.	
	<b>b</b> )	Grows exponentially.	
	c)	Increase exponentially.	
	d)	Both (b) and (c).	
			Answer: (d)
11.	_	al x (t) is said to be power signal if:	
	,	$0 < P < \infty$ and $E = \infty$	
	,	0 < P < E  and  E = 0	
	,	$0 < P < \infty$ and $E = 0$	
	a)	None of the above	Answore (a)
			Answer: (a)
12.	The ur	nit impulse function is also known as:	
	a)	Dirac Delta function.	
	<b>b</b> )	Step function.	
	c)	Both (a) and (b).	
	d)	None of the above.	
			Answer: (a)
13.	A sign	al cannot be both an energy signal and a power signal.	
	a)	False.	
	b)	True.	
	c)	May be.	
	d)	None of the above.	A (1)
			Answer: (b)
14	The di	screte-time unit impulse function $\delta$ [n] is defined as:	
17.			
	a)	$\delta[n] = \begin{cases} 1 & \text{for } n \neq 0 \end{cases}$	
	L	$\delta[n] = \begin{cases} 0 & for  n = 0 \\ 1 & for  n \neq 0 \end{cases}$ $\delta[n] = \begin{cases} 1 & for  n = 0 \\ 0 & for  n \neq 0 \end{cases}$	
	D)	$0 \ln 1 - 0$ for $n \neq 0$	
	c)	$\delta[n] = \begin{cases} 1 & for  n > 0 \\ 0 & for  n < 0 \end{cases}$	
	-,	0   for   n < 0	

Answer: (b)

d) None of the above.

15.	The co	onvolution of x (t) and h (t) is defined by:	
	a)	$y(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau)dt$	
	b)	$y(t) = \int_{-\infty}^{\infty} [x(\tau) + h(t - \tau)] d\tau$	
		$y(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau)d\tau$	
		None of the above.	
	•	Trone of the doore.	Answer: (c)
16.	If the	output is a scaled version of its input, then the input function is called	as:
	a)	Eigenvalue of the system.	
		Eigenfunction of the system.	
	· ·	Both (a) and (b).	
	d)	None of the above.	<b>A</b> (1)
			Answer: (b)
17	Memo	ry in a discrete time system is analog if:	
17.		Energy storage in a continuous time system.	
	b)	Memory in a continuous time system.	
	c)	Sampled memory of a continuous time LTI system.	
	d)	None of the above.	
			Answer: (a)
18.	The sy	$y(t) = x(t) + \frac{1}{3}x(t-3)$ is:	
	a)	Non-causal system.	
	b)	Causal system.	
		Partly A and partly B.	
	d)	None of the above.	
			Answer: (b)
19	Two s	equences $x_1$ (n) and $x_2$ (n) are related by $x_2$ (n) = $x_1$ (-n). In the z-domain	ain their
	ROC's		ani, men
	a)	The same.	
	<b>b</b> )	Reciprocal of each other.	
	c)	Negative of each other.	
	d)	None of the above.	
			Answer: (b)
20			
20.	a)	data have discrete states and take discrete values.  Digital.	
	a)	Digital.	

Answer: (a)

b) Analog.c) (a) or (b).

d) None of the above.

21. The Fourier transform (FT) of a function x [n] is  $X(e^{j\omega})$ . The FT of nx[n] will be:

a) 
$$\frac{dx(t)}{dt}$$

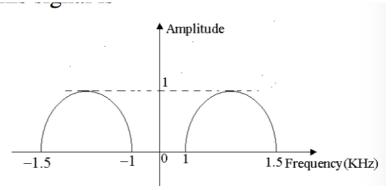
b) 
$$jfX(e^{j\omega})$$
.

c) 
$$j \frac{dX(e^{j\omega})}{d\omega}$$
.

d) None of the above.

Answer: (c)

**22.** An analog signal has the spectrum shown below. The minimum sampling rate needed to completely represent this signal is:



- a) 1 KHz.
- **b)** 2 KHz.
- c) 3 KHz.
- d) None of the above.

Answer: (a)

23. The impulse response of a system is  $h[n] = a^n u[n]$ . The condition for the system to be BIBO stable is:

- a) "a" is real and positive.
- **b)** "a" is real and negative.
- c) |a| > 1.
- d) |a| < 1.

Answer: (d)

**24.** If  $R_1$  is the region of convergence of x (n) and  $R_2$  is the region of convergence of y (n), then the region of convergence of x (n) convoluted y (n) is:

a) 
$$R_1 + R_2$$
.

- **b)**  $R_1 R_2$ .
- c)  $R_1 \cap R_2$ .
- d)  $R_1 \cup R_2$ .

Answer: (c)

25.	The continuous time system described by $y(t) = x(t^2)$ is:	
	a) Causal, linear and time varying.	
	b) Causal, non-linear and time varying.	
	c) Non-causal, non-linear and time-invariant.	
	d) Non-causal, linear and time-invariant.	
		Answer: (d)
26.	$x[n] = a^{ n },  a  < 1 \text{ is:}$	
	a) An energy signal.	
	b) A power signal.	
	c) Neither energy nor a power signal.	
	d) None of the above.	
		Answer: (a)
27	A band pass signal extends from 1 KHz to 2 KHz. The minimum sampling f	reguency
21.	needed to retain all information in the sampled signal is:	requeries
	a) 1 KHz.	
	a) 1 KHz. b) 2 KHz.	
	c) 3 KHz.	
	d) None of the above.	
	a) Trone of the doore.	Answer: (b)
28.	The region of convergence of the z-transform of the signal $2^n u[n] - 3^n u[$	-n-1] is:
	a) $ z  > 1$ .	_
	b) $ z  < 1$ .	
	c) $2 <  z  < 3$ .	
	d) Does not exist.	
	u) Boos not exist.	Answer: (c)
20	The number of possible regions of convergence of the function $\frac{(e^{-2}-2)z}{(z-e^{-2})(z-2)}$	10.
<i>2)</i> .	( /()	15.
	a) 1.	
	b) 3.	
	c) 2.	
	d) None of the above.	
		Answer: (b)
30.	Given a unit step function u (t), its time-derivative is:	
	a) A unit impulse.	
	b) Another step function.	
	c) A unit ramp function.	
	d) None of the above.	Answer (a)
		Answer: (a)

The frequency response of a system with $h[n] = \delta[n] - \delta[n-1]$ is given by:		
a) $\delta(\omega) - \delta(\omega - 1)$ .		
b) $u(\omega) - u(\omega - 1)$ .		
c) $1 - e^{-j\omega}$ .		
d) $1 - e^{j\omega}$ .		
	Answer: (b)	
32. z-transform converts convolution of time-signals to:		
a) Multiplication.		
b) Addition.		
c) Division.		
d) None of the above.		
	Answer: (a)	
33. The Fourier transform of u [n] is:		
a) $\frac{1}{1-e^{-\omega}}$ .		
b) $\frac{1}{1-e^{-j\omega}}$ .		
c) $\frac{1}{j2\pi f}$ .		
d) None of the above.		
	Answer: (d)	
	1 •	
34. The system having input x [n] related to output y [n] as $y[n] = log_{10} x[n]$	1S:	
a) Nonlinear, causal, not stable.		
<ul><li>b) Nonlinear, non-causal, not stable.</li><li>c) Nonlinear, causal, stable.</li></ul>		
d) None of the above.		
a) Trone of the doore.	Answer: (c)	
<b>35.</b> To obtain $x (4-2n)$ from the given signal x [n], the following procedure (continuous)	or priority)	
rule is used for operations on the independent variable n:		
a) Time scaling → Time shifting → Reflection		
b) Time shifting → Time scaling → Reflection		
c) Reflection → Time shifting → Time scaling.		
d) None of the above.		
	Answer: (b)	
26. The unit stap response of a system with impulse response $h[n] = S[n] - S$	[n _ 1] is:	
36. The unit step-response of a system with impulse response $h[n] = \delta[n] - \delta$	[n-1] 18.	
a) $\delta[n]$ .		
b) $\delta[n-1]$ .		
c) $u[n]$ .		

Answer: (a)

d) None of the above.

- 37. The ROC of the z-transform of the signal  $x[n] = \{2,1,1,2\}$ ; n(0) = 1 is:
  - a) All z, except z = 0.
  - b) All z, except  $z = \infty$ .
  - c) All z, except z = 0 and  $z = \infty$ .
  - **d)** None of the above.

Answer: (c)

- **38.** A continuous-time periodic signal x (t), having a period T, is convolved with itself. The resulting signal is:
  - a) Not periodic.
  - **b)** Periodic having a period T.
  - c) Periodic having a period 2T.
  - d) None of the above.

Answer: (b)

- 39. If the Fourier series coefficients of a signal are periodic then the signal must be:
  - a) Continuous-time, periodic.
  - b) Continuous-time, non periodic.
  - c) Discrete-time, non periodic.
  - d) Discrete-time, periodic.

Answer: (d)

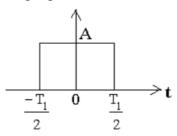
- 40. Let  $H(e^{j\omega})$  be the frequency response of a discrete-time LTI system, and  $H_1(e^{j\omega})$  be the frequency response of its inverse. Then:
  - a)  $H(e^{j\omega})H_1(e^{j\omega}) = 1$ .
  - **b**)  $H(e^{j\omega})H_1(e^{j\omega}) = \delta(\omega)$ .
  - c)  $H(e^{j\omega}) * H_1(e^{j\omega}) = \delta(\omega)$ .
  - d) None of the above.

Answer: (a)

- 41. The transfer function of a stable system is  $H(z) = \frac{1}{1 0.5z^{-1}} + \frac{1}{1 2z^{-1}}$ . Its impulse response will be:
  - a)  $(0.5)^n u[n] (2)^n u[n]$ .
  - b)  $-(0.5)^n u[n-1] + (2)^n u[n]$ .
  - c)  $(0.5)^n u[n] (2)^n u[-n-1]$ .
  - d) None of the above.

Answer: (c)

**42.** The average power of the following signal is:



- **a)**  $\frac{A^2}{2}$ .
- **b)**  $A^2$ .
- c)  $A^2T_1$ .
- d) None of the above.

Answer: (c)

**43.** Convolution is used to find:

- a) The impulse response of an LTI system.
- **b)** Frequency response of a system.
- c) The phase response of a LTI system.
- d) The time response of a LTI system.

Answer: (d)

**44.** The Fourier transform of a rectangular pulse is:

- a) Sinc function.
- **b)** Another rectangular pulse.
- c) Triangular pulse.
- d) None of the above.

Answer: (a)

**45.** The property of Fourier transform which states that the compression in time domain is equivalent to expansion in the frequency domain is:

- a) Duality.
- **b)** Frequency shifting.
- c) Scaling.
- d) None of the above.

Answer: (c)

46. What is the Nyquist frequency for the signal  $x(t) = 3\cos 50\pi t + 10\sin 300\pi t - \cos 100\pi t$ ?

- a) 100 Hz.
- **b)** 300 Hz.
- c) 60 Hz.
- d) None of the above.

Answer: (b)

a	) Gaussian.		
b	o) Sinc.		
c	Pulse.		
d	I) Impulse.		
		Answer: (d)	
<b>48.</b> The	z-transform of $\delta[n-m]$ is:		
a	$z^{-m}$ .		
b	$z^m$ .		
c	$\frac{1}{z}$ .		
d	None of the above.		
		Answer: (a)	
<b>49.</b> The area under the curve $\int_{-\infty}^{\infty} \delta(t) dt$ is:			
a	n) ∞.		
b	O) Unity.		
	9) 0.		
d	None of the above.		
		Answer: (b)	
	a stable system:		
a	z  > 1.		
b	z  = 1.		
c	z  < 1.		
d	None of the above.		
		Answer: (c)	

**47.** The function which has its Fourier transform, Laplace transform and Z-transform unity is: