Signal & Systems Lecture #2

13th March 18

Continuous & Discrete Signals

Classification of Signals

Periodic vs Aperiodic

 \pm Definition-1: A continuous time signal $x(t)$ is periodic if there is a $constantT > o$ such that:

$$
x(t) = x(t+T), \quad for \quad all \quad t \in R
$$

 \div Definition-2: A discrete time signal x[n] is periodic if there is an integer constant $N > o$ such that:

$$
x[n] = x[n+N], \quad for \quad all \quad n \in \mathbb{Z}
$$

- \div Signals do not satisfy the periodicity conditions are called aperiodic signals.
- \div T_o is called the fundamental period of x(t) if it is the smallest value of T >o satisfying the periodicity condition. The number $\omega_0 = \frac{2\pi}{T}$ is called the fundamental frequency of $x(t)$. T_{0}

Periodic vs Aperiodic (cont.)

 \div N_o is called the fundamental period of x[n] if it is smallest value of $N > o$ where $N \varepsilon Z$ satisfying the periodicity condition. The number $\frac{\Omega_0}{\Omega} = \frac{m}{N}$ is called the fundamental frequency of x[n]. 2π $=\frac{m}{\sqrt{m}}$ *N*

Example #1

 \div Determine the fundamental period of the following signals:

$$
(a): e^{j3\pi t/5}
$$

$$
(b): e^{j3\pi n/5}
$$

Even & Odd Signals

- \div An even signal is any signal f such that $f(t) = f(-t)$.
- \div A signal x(t) or x[n] is referred to as an even signal if it is identical to its time-reversed counterpart, i.e., with its reflection about the origin.
- \div An odd signal on the other hand is a signal f such that $f(t) = (f(-t)).$
- \pm Any signal can be written as a combination of an even and odd signal, i.e., every signal has an odd-even decomposition.

$$
f(t) = \frac{1}{2} (f(t) + f(-t)) + \frac{1}{2} (f(t) - f(-t))
$$

Even & Odd Signals (cont.)

❖ The all-zero signal is both even and odd. Any other signal cannot be both even and odd, but may be neither.

Energy & Power

• The total energy of a continuous time signal $x(t)$, where $x(t)$ is defined for $-\infty < t < \infty$, is

$$
E_{\infty} = \int_{-\infty}^{\infty} x^2(t) dt = \lim_{T \to \infty} \int_{-T}^{T} x^2(t) dt
$$

 $\cdot \cdot$ The time-average power of a signal is:

$$
P_{\infty} = \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} x^2(t) dt
$$

- An energy signal is a signal with finite E_∞. For an energy signal, P_∞ $=0.$
- ◆ A power signal is a signal with finite, nonzero P_∞. For a power signal, E_∞=∞.

Energy & Power (cont.)

❖ The total energy of a discrete-time signal is defined by:

$$
E_{\infty} = \sum_{n=-\infty}^{\infty} x^2 \left[n \right] = \lim_{N \to \infty} \sum_{n=-N}^{N} x^2 \left[n \right]
$$

❖ The time-average power is:

$$
P_{\infty} = \lim_{N \to \infty} \frac{1}{2N+1} \sum_{n=-N}^{N} x^2 [n]
$$

Continuous-Time Complex Exponential

 \cdot The continuous-time complex exponential signal is of the form:

 $x(t) = Ce^{at}$, *where C*, $a \in C$

◆ Depending upon the values of these parameters, the complex exponential can exhibit several different characteristics.

Real Exponential Signals

- \cdot If C and a are real there are basically two types of behaviour.
- \cdot If a is positive, then as t increase $x(t)$ is a growing exponential, i.e., when a > 0.
- \cdot If a is negative then x(t) is a decaying exponential, i.e., when a<0.
- ◆ When a=o then x(t) is constant.

Periodic Complex Exponential

- Let's consider the case where a is purely imaginary, i.e., $a = j\omega_{\rm o}$, $\omega_{\rm o}$ belongs to R.
- \div Since C is a complex number, we have: $C = Ae^{j\theta}$ where A, θ belongs to R.

• Consequently:
$$
x(t) = Ce^{j\omega_0 t} = Ae^{j\theta}e^{j\omega_0 t}
$$

= $Ae^{j(\omega_0 t + \theta)} = A\cos(\omega_0 t + \theta) + jA\sin(\omega_0 t + \theta)$

 \cdot The real and imaginary parts of $x(t)$ are: $\text{Re}\left\{x(t)\right\} = A\cos\left(\omega_0 t + \theta\right)$ $\text{Im}\left\{x(t)\right\} = A\sin\left(\omega_0 t + \theta\right)$

Periodic Complex Exponential (cont.)

• We can think of $x(t)$ as a pair of sinusoidal signals of the same amplitude A, ω_0 and phase shift θ with one a cosine and the other a sine.

Periodic complex exponential function $x(t)$ = Ce^{jωot}, C=1, ω₀=2π

Periodic Complex Exponential (cont.)

- \therefore $x(t) = Ce^{j\omega_0 t}$ is periodic with:
	- $\cdot \cdot \cdot$ Fundamental period: $T_0 = 2\pi/|\omega_0|$
	- $\cdot \cdot$ Fundamental frequency: $|ω_0|$
- \cdot the second claim is the immediate result from the first claim. To show the first claim, we need to show that $x(t+T_0) = x(t)$ and no smaller T₀ can satisfy the periodicity criteria.

$$
x(t+T_0) = Ce^{j\omega_0\left(t + \frac{2\pi}{|\omega_0|}\right)} = Ce^{j\omega_0 t}e^{\pm j2\pi}
$$

= Ce^{j\omega_0 t} = x(t)

It is easy to show that T_o is the smallest period.

General Complex Exponential

- The most general case of a complex exponential can be expressed and interpreted in terms of the two cases: the real exponential and the periodic complex exponential.
- Consider a complex exponential Ce^{at}, where C is expressed in polar form and a in rectangular form. I.e., $C = |C|e^{j\theta}$
- \Leftrightarrow And:

$$
a = r + j\omega_0
$$

 $\mathbf{\hat{v}}$ Then:

$$
Ce^{at} = |C|e^{j\theta}e^{(r+j\omega_0)t} = |C|e^{rt}e^{j(\omega_0t+\theta)}
$$

Using Euler's relation, we can expand this further as:

$$
Ce^{at} = |C|e^{rt} \cos(\omega_0 t + \theta) + j|C|e^{rt} \sin(\omega_0 t + \theta)
$$

General Complex Exponential(cont.)

- \cdot Thus for r=0, the real and imaginary parts of a complex exponential are sinusoidal.
- For r>0 they correspond to sinusoidal signals multiplied by a growing exponential.
- For $r < o$, they correspond to sinusoidal signals multiplied by a decaying exponential.
- As shown below: (a) is growing sinusoidal signal when r>o, (b) is decaying sinusoid when $r < 0$.

General Complex Exponential(cont.)

◆ Sinusoidal signals multiplied by decaying exponentials are commonly referred to as damped signals.

Discrete-Time Complex Exponential

◆ A discrete-time complex exponential function has the form: $x[n] = Ce^{\beta n}$

 $\cdot \cdot$ Where C, β belongs to Complex. Letting $\alpha = e^{\beta}$: $x[n] = C\alpha^n$

Real-Valued Complex Exponential

- \cdot x[n] is a real-valued complex exponential when C belongs to R and α belongs to R.
- In this case, $x[n] = C\alpha^n$ is a monotonic decreasing function when o < α <1 and is a monotonic increasing when α > 1.

Complex-Valued Complex Exponential

 \cdot x[n] is a complex-valued complex exponential when C, α belongs to complex.

• In this case C and α can be written as:

$$
C = |C|e^{j\theta} \quad and \quad \alpha = |\alpha|e^{j\Omega_0}
$$

Comsequently,

$$
x[n] = C\alpha^{n} = |C|e^{j\theta} (|\alpha|e^{j\Omega_{0}})^{n}
$$

= $|C||\alpha|^{n} e^{j(\Omega_{0}n+\theta)}$
= $|C||\alpha|^{n} \cos(\Omega_{0}n+\theta) + j|C||\alpha|^{n} \sin(\Omega_{0}n+\theta)$

Complex-Valued Complex Exponential(cont.)

\cdot Three cases can be considered here:

- When $|\alpha|=1$, then $x[n] = |C|\cos(\Omega_0n+\theta) + j|C|\sin(\Omega_0n+\theta)$ and it has sinusoidal real and imaginary parts (not necessarily periodic though).
- When $|\alpha| > 1$, then $|\alpha|^n$ is a growing exponential, so the real and imaginary parts of $x[n]$ are the product of this with sinusoids.
- When $|\alpha|$ < 1, then the real and imaginary parts of x[n] are sinusoids sealed by a decaying exponential.

(a) Growing Discrete-time sinusoidal signals (b) decaying discrete time sinusoid

Periodic Complex Exponential

 \cdot Consider $x[n] = Ce^{i\Omega_0 n}$, $\Omega_0 \in R$ We want to study the condition for x[n] to be periodic.

 $\cdot \cdot$ The periodicity condition requires that, for some N>o,

$$
x[n+N] = x[n], \quad \forall n \in \mathbb{Z}
$$

 \cdot Since $x[n] = Ce^{j\Omega_0 n}$, it holds that:

$$
e^{j\Omega_0(n+N)} = e^{j\Omega_0 n}e^{j\Omega_0 N} = e^{j\Omega_0 n}, \quad \forall n \in \mathbb{Z}
$$

 \div This is equivalent to:

$$
e^{j\Omega_0 N} = 1
$$
 or $\Omega_0 N = 2\pi m$, for some $m \in Z$

Periodic Complex Exponential (cont.)

 \cdot Therefore, the condition for periodicity of x[n] is:

$$
\Omega_0 = \frac{2\pi m}{N}
$$

 $\cdot \cdot$ For some m belongs to Z and some N>0, N belongs to Z.

Periodic Complex Exponential (cont.)

- Thus x[n] = $e^{j\Omega_{on}}$ is periodic if and only if Ω_{o} is a rational multiple of 2π.
- \cdot The fundamental period is:

$$
N = \frac{2\pi m}{\Omega_0}
$$

• Where we assume that m and N are relatively prime, gcd (m,n) =1, i.e., m/N is in reduced form.

Impulse & Step Functions

Discrete-Time Impulse & Step Functions

• The discrete-time unit impulse signal δ [n] is defined as:

$$
\delta(n) = \begin{cases} 1 & \text{for } n = 0 \\ 0 & \text{for } n \neq 0 \end{cases}
$$

* The discrete-time unit step signal u[n] is defined as:

$$
u(n) = \begin{cases} 1 & \text{for} \quad n \ge 0 \\ 0 & \text{for} \quad n < 0 \end{cases}
$$

Relation B/w Unit Impulse & Unit Step Sequences

- ◆ Discrete time unit impulse is the first difference of the discrete time unit step. l.e.; $\delta[n]=\upsilon[n]-\upsilon[n-1]$
- \cdot Discrete time unit step is the running sum of the discrete time unit impulse or unit sample. i.e.;

$$
u[n] = \sum_{m=-\infty}^{n} \delta[m]
$$

Property of δ[n]

❖ Sampling Property:

- By the definition $\delta[n]$, $\delta[n-n_d] = 1$ if $n=n_0$ and o otherwise. \div Therefore, $x[n]\delta[n-n_0]=\begin{cases} x[n], & n=n_0 \end{cases}$ 0, $n \neq n_0$ q1
| ⎨ ⎪ $\begin{bmatrix} \frac{1}{2} & \frac{1}{2$ $= x \left[n_0 \right] \delta \left[n - n_0 \right]$
- As a special case when n_0 =0, we have x[n] $\delta[n]$ =x[o] $\delta[n]$.
- When a signal x[n] is multiplied with $\delta[n]$, the output is a unit impulse with amplitude x[0].

Property of δ[n] (cont.)

Property of δ[n] (cont.)

\div Shifting Property:

• Since x[n] $\delta[n] = x[0] \delta[n]$ and $\delta[n] = x[0] \delta[n]$ and $\delta[n] = x[0] \delta[n]$ and $\delta[n] = x[0] \delta[n]$ *x*[*n*]^δ [*n*] *n*=−∞ ∞ $\sum x[n]\delta[n] = \sum x[0]\delta[n]$ *n*=−∞ ∞ $\sum x[0]\delta[n] = x[0]\sum \delta[n]$ *n*=−∞ ∞ $\sum \delta[n] = x[0]$ $\delta\lfloor n\rfloor$ *n*=−∞ $\sum \delta[n] = 1$

∞

 \div And similarly:

$$
\sum_{n=-\infty}^{\infty} x[n] \delta[n - n_0] = \sum_{n=-\infty}^{\infty} x[n_0] \delta[n - n_0] = x[n_0]
$$

 Γ

❖ In general, the following result holds:

$$
\sum_{n=a}^{b} x[n]\delta[n-n_0] = \begin{cases} x[n_0], & \text{if } n_0 \in [a,b] \\ 0, & \text{if } n_0 \notin [a,b] \end{cases}
$$

Continuous-Time Impulse & Step Functions

◆ The Dirac delta is defined as:

$$
\delta(t) = \begin{cases} 1 & \text{for } t = 0 \\ 0 & \text{for } t \neq 0 \end{cases}
$$

$$
\int_{0}^{\infty} \delta(t) dt = 1
$$

❖ Where:

$$
\int_{-\infty}^{\infty} \delta(t) dt = 1
$$

❖ The unit step function is defined as:

$$
u(t) = \begin{cases} 1 & \text{for } t \ge 0 \\ 0 & \text{for } t < 0 \end{cases}
$$

Property of δ(t)

 \cdot The properties of $\delta(t)$ are analogous to the discrete-time case:

 \div Sampling Property:

 $x(t)\delta(t) = x(0)\delta(t)$

- Note that $x(t)$ $\delta(t) = x(o)$ when t=0 and $x(t)$ $\delta(t) = o$ when t≠0.
- ❖ Similarly we have:

$$
x(t)\delta(t - t_0) = x(t_0)\delta(t - t_0)
$$

for any $t_0 \in R$

Property of δ **(t) (cont.)**

\div Shifting Property:

 \cdot The shifting property follows from the sampling property.

 \cdot Integrating x(t) δ (t) yields:

$$
\int_{-\infty}^{\infty} x(t) \delta(t) dt = \int_{-\infty}^{\infty} x(0) \delta(t) dt = x(0) \int_{-\infty}^{\infty} \delta(t) dt = x(0)
$$

Similarly, one can show that:

$$
\int_{-\infty}^{\infty} x(t) \delta(t - t_0) dt = x(t_0)
$$

Continuous & Discrete Systems

Fundamentals of Systems

- \cdot A system in the broadcast sense are an interconnection of components, devices or subsystems.
- A system can be viewed as a process in which input signals are transformed by the system or cause the system to respond in some way resulting in other signals as output.
- ◆ A continuous time system is a system in which continuous time input signals are applied and result in continuous time output signals. The input-output relation is represented by the following notation: $x(t) \rightarrow y(t)$.

Systems (cont.)

◆ Similarly a discrete time system is a system that transforms discrete time inputs into discrete time outputs and represented symbolically as: $x[n] \rightarrow y[n]$.

Example #2

- \div Consider the RC circuit depicted below:
- If we regard $v_{s}(t)$ as the input signal and $v_{c}(t)$ as the output signal, then we can use simple circuit analysis to derive an equation describing the relationship between the input and output.
- ◆ Specifically from Ohm's law the current i(t) through the resistor is proportional (with proportionality constant 1/R) to the voltage drop across the resistor; i.e.,

Example #2 (cont.)

$$
i(t) = \frac{v_s(t) - v_c(t)}{R}
$$

◆ Similarly, using the defining constitutive relation for a capacitor, we can relate i(t) to the rate of change with tome of the voltage across the capacitor:

$$
i(t) = C \frac{dv_c}{dt}
$$

 \cdot Equating the right hand side of above two equations, we obtain a differential equation describing the relationship between the input $v_s(t)$ and the output $v_c(t)$:

$$
\frac{dv_c}{dt} + \frac{1}{RC}v_c\left(t\right) = \frac{1}{RC}v_s\left(t\right)
$$

Thank You