

# Signal & Systems

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Lecture # 6

Revision Before Mids

5<sup>th</sup> November 18

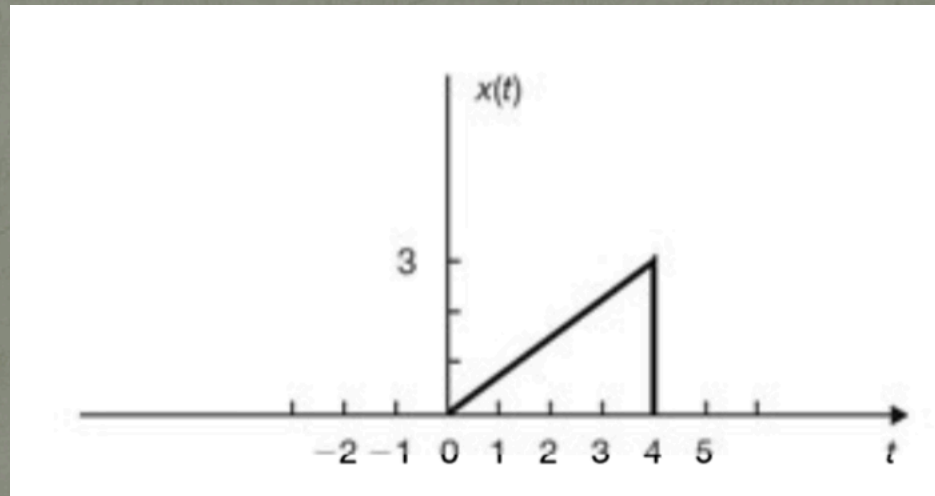
# Signal Operations

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# Example #1

- A continuous-time signal  $x(t)$  is shown below. Sketch and label the following signal:

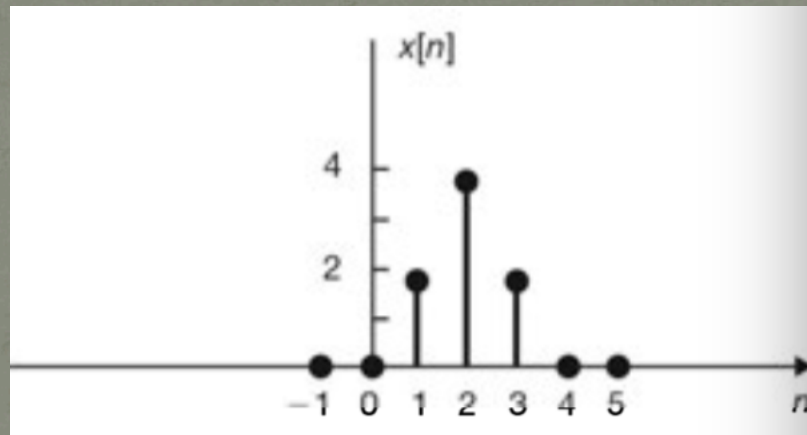
$$-x(2t - 2)$$



## Example #2

- A discrete-time signal  $x[n]$  is shown below. Sketch and label the following signal:

$$2x[2n+3]$$

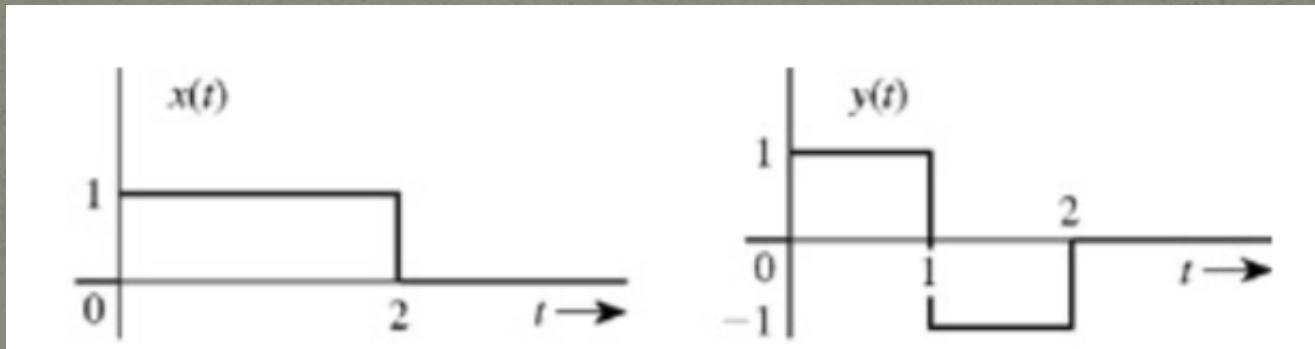


# Energy & Power

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# Example #3

- Find the energies of the pair of signals  $x(t)$  and  $y(t)$  shown below. Sketch and find the energies of signals of  $x(t)+y(t)$  and  $x(t)-y(t)$ .



## Example #4

- Determine whether the following signal is power signal or not:

$$x[n] = 2e^{j3n}$$

Periodic/Aperiodic

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# Example #5

- Determine whether or not each of the following signals is periodic. If a signal is periodic, determine its fundamental period:
  - (1):  $x(t) = \cos t + \sin \sqrt{2}t$
  - (2):  $x[n] = e^{j(\pi/4)n}$

# Even & Odd

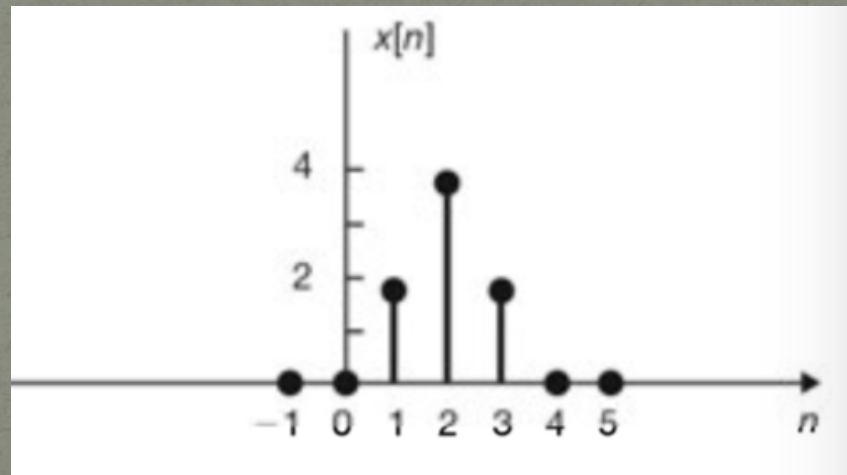
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## Example #6

- Find the even and odd components of  $x(t) = e^{jt}$ .

# Example #7

- Sketch and label the even and odd components of the signal shown below:

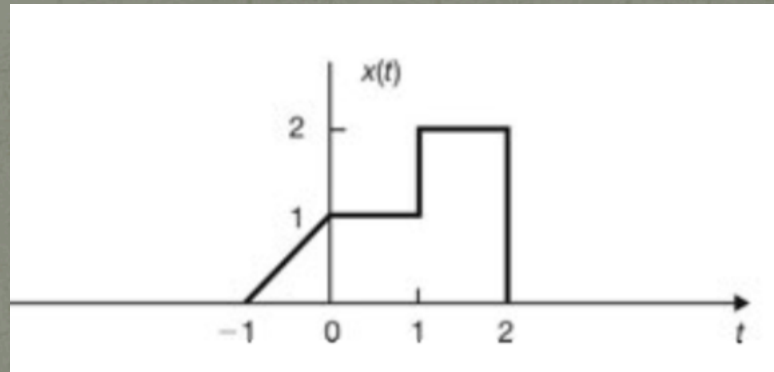


# Unit Step & Unit Impulse Functions

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# Example #8

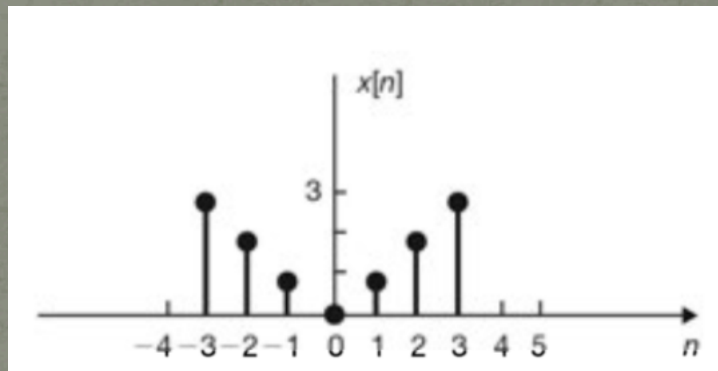
- A continuous time signal  $x(t)$  is shown below. Sketch and label the following signal.



- (1):  $x(t) u(1-t)$

# Example #9

- A discrete time signal  $x[n]$  is shown below. Sketch and label the following signal.



- (1):  $x[n]\delta[n]$

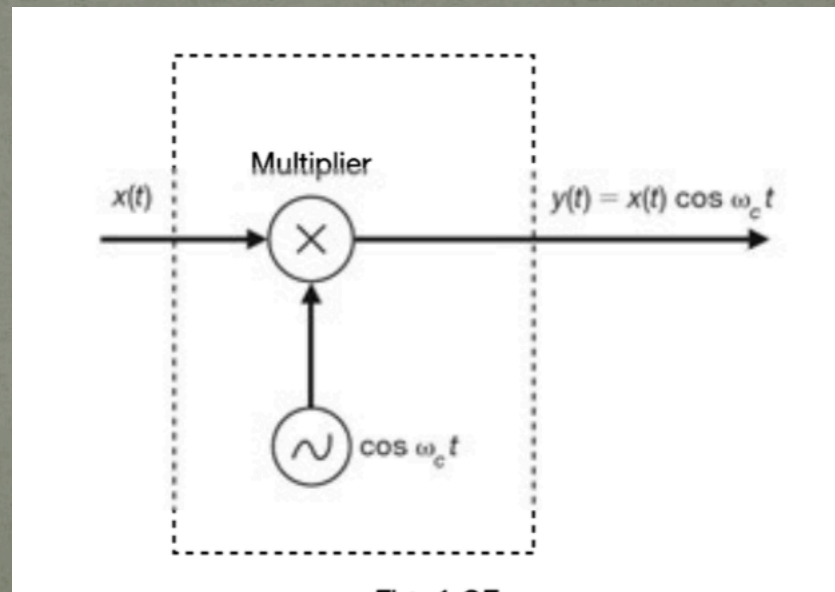
# Continuous & Discrete Systems

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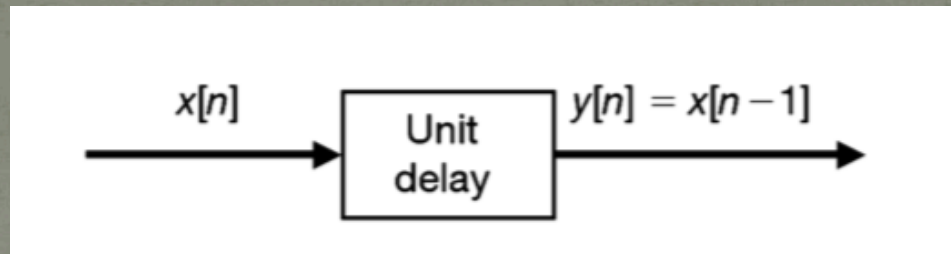
# Example #10

- Consider the system shown below. Determine whether it is:
  - (1): Memoryless
  - (2): Causal
  - (3): Linear
  - (d): Time-invariant
  - (e): Stable



# Example #11

- The discrete time system is shown below is known as the unit delay element. Determine whether it is:
  - (1): Memoryless
  - (2): Causal
  - (3): Linear
  - (d): Time-invariant
  - (e): Stable



# Convolution & Properties of LTI

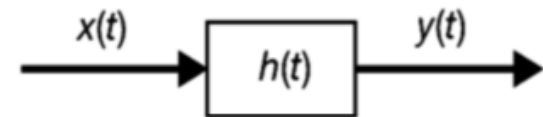
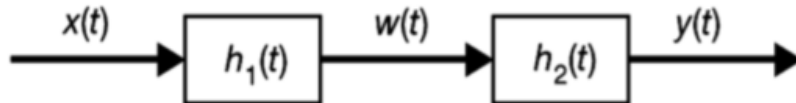
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# Example #12

- The system shown below is formed by connecting two systems in cascade. The impulse responses of the systems are given by  $h_1(t)$  and  $h_2(t)$ , respectively and:

$$h_1(t) = e^{-2t}u(t) \quad \text{and} \quad h_2(t) = 2e^{-t}u(t)$$

- (a): Find the impulse response  $h(t)$  of the overall system.
- (b): Determine if the overall system is BIBO stable.



The End

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