



# ISRA UNIVERSITY

Islamabad Campus

Department of Electrical Engineering

Program: B.E. (Electrical)

Semester - Fall 2018

**Solution**

EE313- Signal & Systems

Quiz – 3

Marks: 30

Handout Date: 11/01/2019

**Question # 1:**

Consider an LTI system for which the input  $x[n]$  and the output  $y[n]$  satisfy the linear constant coefficient difference equation:

$$y[n] - \frac{1}{2}y[n-1] = x[n] + \frac{1}{3}x[n-1]$$

**Solution:**

The use of the Fourier transform simplifies the analysis of the difference equation:

$$\begin{aligned}y[n] - \frac{1}{2}y[n-1] &= x[n] + \frac{1}{3}x[n-1] \\Y(e^{j\omega}) - \frac{1}{2}e^{-j\omega}Y(e^{j\omega}) &= X(e^{j\omega}) + \frac{1}{3}e^{-j\omega}X(e^{j\omega}) \\Y(e^{j\omega})\left(1 - \frac{1}{2}e^{-j\omega}\right) &= X(e^{j\omega})\left(1 + \frac{1}{3}e^{-j\omega}\right) \\H(e^{j\omega}) = \frac{Y(e^{j\omega})}{X(e^{j\omega})} &= \frac{1 + \frac{1}{3}e^{-j\omega}}{1 - \frac{1}{2}e^{-j\omega}} \\H(e^{j\omega}) = \frac{Y(e^{j\omega})}{X(e^{j\omega})} &= \frac{1}{1 - \frac{1}{2}e^{-j\omega}} + \frac{1}{3} \frac{e^{-j\omega}}{1 - \frac{1}{2}e^{-j\omega}}\end{aligned}$$

Taking the inverse Fourier transform of  $H(e^{j\omega})$ , we get:

$$h[n] = \left(\frac{1}{2}\right)^n u[n] + \frac{1}{3}\left(\frac{1}{2}\right)^{n-1} u[n-1]$$

---

**Question # 2:**

Determine the Fourier series coefficients of the following signal:

$$x[n] = \cos \frac{\pi}{4} n$$

**Solution:**

$$x[n] = \cos \frac{\pi}{4} n$$

Using Euler's identity:

$$x[n] = \frac{e^{\frac{j\pi}{4}n}}{2} + \frac{e^{-\frac{j\pi}{4}n}}{2}$$

The fundamental frequency,  $\omega_0 = \frac{\pi}{4}$ .

Where:

$$a_1 = \frac{1}{2}, a_{-1} = \frac{1}{2}$$

Otherwise  $a_k = 0$ .

Hence, the discrete Fourier series of  $x[n]$  is:

$$x[n] = \frac{e^{\frac{j\pi}{4}n}}{2} + \frac{e^{-\frac{j\pi}{4}n}}{2}$$

---

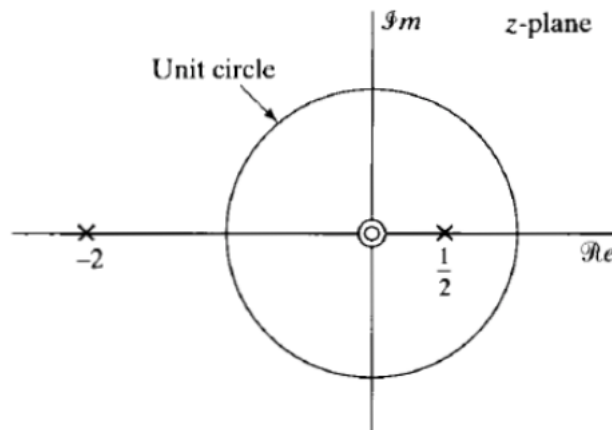
**Question # 3:**

a) Consider a system with system function:

$$H(z) = \frac{1}{1 - \frac{1}{2}z^{-1}} + \frac{1}{1 - 2z^{-1}}, |z| > 2$$

Find  $h[n]$  and also tell whether the system is Causal or not?

b) For the following pole-zero plot, determine that whether the system is both causal and stable or not. If not, then explain why?



**Solution:**

a) Consider a system with system function:

$$H(z) = \frac{1}{1 - \frac{1}{2}z^{-1}} + \frac{1}{1 - 2z^{-1}}, |z| > 2$$

Find  $h[n]$  and also tell whether the system is Causal or not?

**Solution:**

$H(z) = \frac{1}{1 - \frac{1}{2}z^{-1}} + \frac{1}{1 - 2z^{-1}}, |z| > 2$

$h[n] = ?$

**Sol:-**

> Since the ROC for this system function is the exterior of a circle outside the outermost pole, we know that the impulse response is right sided.

> To determine if the system is causal, we then need only check the other condition required for causality, namely that  $H(z)$ , when expressed as a ratio of polynomials in  $z$ , has numerator degree no larger than

the denominator.

→ For this example:

$$H(z) = \frac{1-2z^{-1} + 1-\frac{1}{2}z^{-1}}{(1-\frac{1}{2}z^{-1})(1-2z^{-1})} = \frac{2-\frac{5}{2}z^{-1}}{(1-\frac{1}{2}z^{-1})(1-2z^{-1})}$$

$$H(z) \Rightarrow \frac{2z^2 - \frac{5}{2}z}{z^2 - \frac{5}{2}z - 1}$$

→ The numerator and denominator of  $H(z)$  are both of degree two, and consequently we can conclude that the system is causal.

→ This can also be verified by calculating the inverse transform of  $H(z)$ .

→ Using pair 5 in table of standard z-transform pairs, the impulse response of this system is,

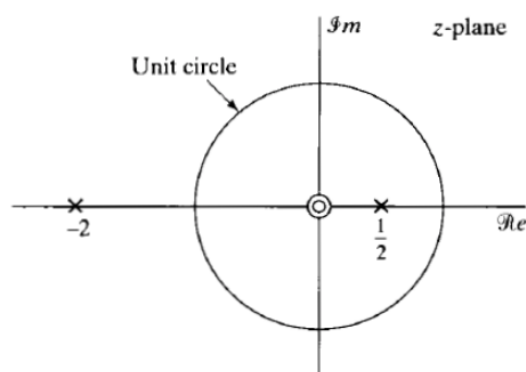
$$h[n] = \left(\frac{1}{2}\right)^n u[n] + (2)^n u[n].$$

→ Since  $h[n] = 0$  for  $n < 0$ , we can confirm that the system is causal.

**Stability:-**

→ If we consider the example #5 for checking stability of the system we see that since the ROC associated is the region  $|z| > 2$  which does not include the unit circle, the system is not stable.

- b) For the following pole-zero plot, determine that whether the system is both causal and stable or not. If not, then explain why?



**Solution:**

A system is causal, as the ROC will extend outwards the outermost pole to infinity.  
 A system is stable, as the unity circle is included in the ROC.

**Good Luck**